## Full Length Research Paper

# Some affine connexions in a generalized structure manifold 

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Accepted 13 January, 2009


#### Abstract

In this paper we have studied some affine connexions in a generalised structure manifold. Certain theorems are have also been proved, which are of great geometrical importance.


Key words: $C^{\infty}$-manifold, generalised structure, generalised metric structure, F - structure, $\pi$ - structure, AMS Subject Classification Number: 53.

## INTRODUCTION

We consider a differentiable manifold $V_{n}$ of differentiability class $C^{\infty}$ and of dimension $n$. Let there exist in $V_{n}$ a tensor field F of the type ( 1,1 ), s linearly independent vector fields $U_{i}, i=1,2 \ldots$ s and s linearly independent 1 -forms $u^{i}$ such that for any arbitrary vector field X , we have

$$
\begin{align*}
& \overline{\bar{X}}=b^{2} X+c u^{i}(X) U_{i},  \tag{1.1}\\
& \overline{U_{i}}=p_{i}^{j} U_{j} \tag{1.2}
\end{align*}
$$

Where
$\mathrm{F}(\mathrm{X}) \stackrel{\text { def }}{=} \bar{X}$ and $b^{2}, \mathrm{c}$ are constants
Then the structure $\left\{\mathrm{F}, u^{i}, U_{i}, p_{i}^{j} ; i, \mathrm{j}=1,2, \ldots \ldots ., \mathrm{s}\right\}$ will be known as generalised structure and $V_{n}$ will be known as generalised structure manifold of order $s$ where $s<n$.

## Agreement 1.1

All the equations which follow hold for arbitrary vector fields X, Y, Z, $\qquad$ etc.
Now replacing $X$ by $\bar{X}$ in (1.1), we get

[^0]\[

$$
\begin{equation*}
\overline{\bar{X}}=b^{2} \bar{X}+c u^{i}(\bar{X}) U_{i} \tag{1.3}
\end{equation*}
$$

\]

Operating $F$ in (1.1), we get

$$
\overline{\bar{X}}=b^{2} \bar{X}+c u^{i}(X) \overline{U_{i}}
$$

Using (1.2) in above, we get

$$
\begin{equation*}
\overline{\bar{X}}=b^{2} \bar{X}+c u^{i}(X) p_{i}^{j} U_{j} \tag{1.4}
\end{equation*}
$$

From (1.3) and (1.4), we have

$$
\begin{equation*}
u^{i}(\bar{X})=u^{j}(X) p_{j}^{i} \tag{1.5}
\end{equation*}
$$

Further, operating $F$ in (1.2) and using (1.1) and (1.2), we get

$$
\begin{equation*}
{ }^{(2)} p_{i}^{j}=b^{2} \delta_{i}^{j}+c u^{j}\left(U_{i}\right) \tag{1.6}
\end{equation*}
$$

Where

$$
{ }^{(r)} p_{j}^{i}={ }^{(r-1)} p_{k}^{i} p_{j}^{k}
$$

On generalised structure manifold $V_{n}$, let us introduce a metric tensor g such that $F$ defined by
$' F(X, Y) \stackrel{\text { def }}{=} g(\bar{X}, Y)$ is skew-symmetric, then $V_{n}$ is
called generalised metric structure manifold.
We have on a generalised metric structure manifold $g(\bar{X}, Y)+g(X, \bar{Y})=0$. Replacing $Y$ by $\bar{Y}$ in above equation and using (1.1), we obtain

$$
\begin{equation*}
g(\bar{X}, \bar{Y})+b^{2} g(X, Y)+c u^{i}(X) u^{i}(Y)=0 \tag{1.7}
\end{equation*}
$$

Where

$$
\begin{equation*}
u^{i}(X)=g\left(U_{i,} X\right) \tag{1.8}
\end{equation*}
$$

Then $V_{n}$ satisfying (1.7), (1.8) is called generalised metric structure manifold (Mishra, 1984).

Agreement 1.2: The generalised metric structure manifold will always be denoted by $V_{n}$.

Definitions: (Boothby, 1975; Kobayasi and Nomizu, 1996)

Almost tangent metric manifold: A differentiable manifold $M_{n}$ on which there exists a tensor field F of the type $(1,1)$ such that
$F^{2}=0$
is called an almost tangent manifold and $\{\mathrm{F}\}$ is called an almost tangent structure on $M_{n}$.
On almost tangent manifold, let us introduce a metric g such ' $F$ defined by $\quad F(X, Y) \stackrel{\text { def }}{=} g(\bar{X}, Y)$ is alternating. Then $M_{n}$ is called an almost tangent metric manifold and structure $\{\mathrm{F}, \mathrm{g}\}$ is called an almost tangent metric structure.

Almost Hermite manifold: A differentiable manifold $M_{n}$ on which there exists a tensor field $F$ of the type $(1,1)$ such that

$$
\begin{equation*}
F^{2}=-I_{n} \tag{1.10}
\end{equation*}
$$

is called an almost complex manifold and $\{F\}$ is called an almost complex structure.
An almost complex manifold endowed with an almost complex structure and a metric $g$ such that

$$
\begin{equation*}
g(\bar{X}, \bar{Y})=g(X, Y) \tag{1.11}
\end{equation*}
$$

is called an almost Hermite manifold and structure $\{\mathrm{F}, \mathrm{g}\}$ is called an almost Hermite structure.

Metric $\pi$-structure manifold: (Mishra and Singh, 1975; Duggal, 1969). A differentiable manifold $M_{n}$ on which there exists a tensor field F of the type $(1,1)$ such that

$$
\begin{equation*}
F^{2}=-\lambda^{2} I_{n} \tag{1.12}
\end{equation*}
$$

where $\lambda$ is a non zero complex constant. Then $\{\mathrm{F}\}$ is called a $\pi$-structure or G-F structure and $M_{n}$ is called $\pi$ - structure manifold or G-F structure manifold.
On almost tangent manifold, let us introduce a metric g such that ' $F$ defined by $' F(X, Y) \stackrel{\operatorname{def}}{=} g(\bar{X}, Y)$ is alternating. Then $\{\mathrm{F}, \mathrm{g}\}$ is called metric $\pi$ - structure or H structure and $M_{n}$ is called metric $\pi$-structure manifold or H - structure manifold.

F-Structure Manifold: (Yano, 1963). Let $M_{n}$ be an $n$ dimensional differentiable manifold of class $C^{\infty}$ and let there be a tensor field of the type $(1,1)$ and rank $r(1 \leq r \leq n)$ everywhere such that

$$
\begin{equation*}
F^{3}+F=0 \tag{1.13}
\end{equation*}
$$

Then $\{\mathrm{F}\}$ is called an F -structure and $M_{n}$ is called Fstructure manifold.

Almost Grayan manifold: (Sasaki, 1960): If on an differentiable manifold $M_{n}(\mathrm{n}=2 \mathrm{~m}+1)$ of differentiability class $C^{r+1}$, there exist a tensor field F of the type (1, 1), a 1 - form $u$ and a vector field $U$, satisfying

$$
\begin{equation*}
F^{2}=-I_{n}+\mathrm{u} \otimes \mathrm{U} \tag{1.14}
\end{equation*}
$$

and

$$
\begin{equation*}
\bar{U}=0 \tag{1.15}
\end{equation*}
$$

Then $M_{n}$ is called an almost contact manifold and the structure $\{F, \mathrm{U}, \mathrm{u}\}$ is said to give an almost contact structure to $M_{n}$.
On an almost contact manifold, let us introduce a metric g such that ' $F$ defined by $F(X, Y) \stackrel{\text { def }}{=} g(\bar{X}, Y)$ is skew symmetric. Then $M_{n}$ is called an almost Grayan manifold and the structure $\{\mathrm{F}, \mathrm{g}, \mathrm{U}, \mathrm{u}\}$ is called an almost Grayan structure. In this manifold it can be easily calculated

$$
\begin{equation*}
g(\bar{X}, \bar{Y})=g(X, Y)-u(X) u(Y)=0 \tag{1.16}
\end{equation*}
$$

Torsion tensor A vector valued, skew-symmetric, bilinear function $S$ defined by

$$
\begin{equation*}
S(X, Y) \stackrel{\text { def }}{=} D_{X} Y-D_{Y} X-[X, Y] \tag{1.17}
\end{equation*}
$$

is called torsion tensor of a connexion D in a $C^{\infty}$ manifold $V_{n}$.
For the symmetric or torsion free connexion D , the torsion tensor vanishes.

Curvature tensor: The tensor K of the type (1, 3) defined by

$$
\begin{equation*}
K(X, Y, Z) \stackrel{\text { def }}{=} D_{X} D_{Y} Z-D_{Y} D_{X} Z-D_{[X, Y]} Z \tag{1.18}
\end{equation*}
$$

is called the curvature tensor of the connexion $D$.

## Remark 1.1

It may be noted that $V_{n}$ gives an almost tangent metric manifold ,an almost Hermite manifold, metric $\pi$-structure manifold, F - structure manifold, an almost Grayan manifold and $\left\{\mathrm{F}, \mathrm{g}, u^{1}, u^{2}, U_{1}, U_{2}\right\}$ structure manifold according as $\left(b^{2}=0, \mathrm{c}=0\right) ;\left(b^{2}=-1, \mathrm{c}=0\right) ;\left(b^{2}=\lambda^{r}, \mathrm{c}\right.$ $=0) ;\left(b^{2}=-1, p_{i}^{j}=0\right) ;\left(b^{2}=-1, \mathrm{c}=1, i, \mathrm{j}=1, p_{1}^{1}=0\right)$ and ( $b^{2}=-1, \mathrm{c}=1, p_{i}^{j}+p_{j}^{i}=0 ; i, \mathrm{j}=1,2$ ) respectively.

Affine Connexion D: Let us consider in $V_{n}$ an affine connexion D satisfying (Duggal, 1971; Mishra, 1984)

$$
\begin{equation*}
\left(D_{X} F\right) Y=0 \tag{2.1}
\end{equation*}
$$

and we call it as F -connexion.
(2.1)a is equivalent to

$$
\begin{equation*}
D_{X} \bar{Y}=\overline{D_{X} Y} \tag{2.1}
\end{equation*}
$$

Replacing $Y$ by $\bar{Y}$ and using (1.1), (2.1)a in above, we get

$$
\begin{equation*}
\mathrm{c}\left[u^{i}(Y) D_{X} U_{i}+\left(D_{X} u^{i}\right)(Y) U_{i}\right]=0 \tag{2.1}
\end{equation*}
$$

Theorem (2.1): $\ln V_{n}$, we have

$$
\begin{equation*}
c u^{i}(Y) u^{j}\left(D_{X} U_{i}\right)=-\left(b^{2} \delta_{i}^{j}-{ }^{(2)} p_{i}^{j}\right)\left(D_{X} u^{i}\right)(Y) \tag{2.2}
\end{equation*}
$$

$$
\begin{equation*}
c u^{j}\left(D_{X} U_{i}\right) U_{j}=-\left(b^{2} \delta_{i}^{j}-{ }^{(2)} p_{i}^{j}\right)\left(D_{X} U_{j}\right) \tag{2.3}
\end{equation*}
$$

## Proof

Operating $u^{j}$ in (2.1)c and using (1.6), we get (2.2). Putting $U_{i}$ for Y in (2.1)c and using (1.6), we obtain (2.3).

## Theorem 2.2

In $V_{n}$, we have

$$
\begin{align*}
& S(\bar{X}, \bar{Y})+b^{2} S(X, Y)+c u^{i}(S(X, Y)) U_{i}-\overline{S(\bar{X}, Y)}-\overline{S(X, \bar{Y})} \\
& =-[\bar{X}, \bar{Y}]-b^{2}[X, Y]-c u^{i}([X, Y]) U_{i}+[\overline{\bar{X}}, Y]+\overline{[X, \bar{Y}]} \tag{2.5}
\end{align*}
$$

## Proof

From (2.1)b, we get

$$
\begin{gather*}
D_{\bar{X}} \bar{Y}=\overline{D_{\bar{X}} Y}, D_{\bar{Y}} \bar{X}=\overline{D_{\bar{Y}} X}, \overline{D_{X} \bar{Y}}=\overline{\overline{D_{X} Y}}, \\
D_{Y} \bar{X}  \tag{2.6}\\
=\overline{\overline{D_{Y} X}}
\end{gather*}
$$

Now in view of (1.1), we have
$S(\bar{X}, \bar{Y})+b^{2} S(X, Y)+c u^{i}(S(X, Y)) U_{i}-\overline{S(\bar{X}, Y)}-\overline{S(X, \bar{Y})}$
$=S(\bar{X}, \bar{Y})+\overline{\overline{S(X, Y)}}-\overline{S(\bar{X}, Y)}-\overline{S(X, \bar{Y})}$
Using (1.17) and (2.6) in right hand side of above, we get (2.5). Now, we consider in $V_{n}$ a scalar valued bilinear function $\mu$, vector valued linear function $v$ and a 1 -form $\sigma$ given by,
$\mu(X, Y) \stackrel{\text { def }}{=}$
$\left(D_{Y} u^{i}\right)(\bar{X})-\left(D_{X} u^{i}\right)(\bar{Y})+\left(D_{\bar{Y}} u^{i}\right)(X)-\left(D_{\bar{X}} u^{i}\right)(Y)$
$v(\mathrm{X}) \stackrel{\text { def }}{=}\left(D_{U_{i}} F\right)(X)-\left(D_{X} F\right)\left(U_{i}\right)-D_{\bar{X}} U_{i}$
and

$$
\begin{equation*}
\sigma(\mathrm{X}) \stackrel{\operatorname{def}}{=}\left(D_{X} u^{j}\right)\left(U_{i}\right)-\left(D_{U_{i}} u^{j}\right)(X) \tag{2.9}
\end{equation*}
$$

$i, j=1,2, \ldots \ldots ., s$.

## Theorem (2.3)

$\ln V_{n}$, we have
$\left(b^{2} \delta_{i}^{j}-{ }^{(2)} p_{i}^{j}\right) \mu(X, Y)=$
$c\left[u^{i}(X) u^{j}\left(D_{\bar{Y}} U_{i}\right)-u^{i}(Y) u^{j}\left(D_{\bar{X}} U_{i}\right)-u^{i}(\bar{X})\left(D_{Y} u^{j}\right) U_{i}+u^{i}(\bar{Y})\left(D_{X} u^{j}\right) U_{i}\right]$
(2.10)a
$\left(b^{2} \delta_{i}^{j}-{ }^{(2)} p^{j}{ }_{i}\right) \mu(X, Y)=$
$-c\left[u^{i}(X) u^{j}(v(Y))-u^{i}(Y) u^{j}(v(X))+u^{i}(\bar{X})\left(D_{Y} u^{j}\right) U_{i}-u^{i}(\bar{Y})\left(D_{X} u^{j}\right) U_{i}\right]$
(2.10)b
and
$\left(b^{2} \delta_{i}^{j}-{ }^{(2)} p_{i}^{j}\right) \mu(X, Y)=$
$-c\left[u^{i}(X)\left\{\sigma(\bar{X})+\left(D_{u_{i}} u^{j}\right)(\bar{X})\right\}-u^{i}(Y)\left\{\sigma(\bar{Y})+\left(D_{u_{i}} u^{j}\right)(\bar{Y})\right\}-u^{i}(\bar{X})\left(D_{y} u^{j}\right) U_{i}+u^{i}(\bar{Y})\left(D_{\chi} u^{i}\right) U_{i}\right]$
(2.10) c

## Proof

Replacing $Y$ by $\bar{Y}$ in (2.2), we get
$c u^{i}(\bar{Y}) u^{j}\left(D_{X} U_{i}\right)=-\left(b^{2} \delta_{i}^{j}-{ }^{(2)} p_{i}^{j}\right)\left(D_{X} u^{i}\right)(\bar{Y})$

Replacing $X$ by $\bar{X}$ in (2.2), we get
$c u^{i}(Y) u^{j}\left(D_{\bar{X}} U_{i}\right)=-\left(b^{2} \delta_{i}^{j}-{ }^{(2)} p_{i}^{j}\right)\left(D_{\bar{X}} u^{i}\right)(Y)$

Further by using (2.11), (2.12) in (2.7), we get (2.10)a. Using (2.1)a in (2.8), we get
$v(\mathrm{X})=-\left(D_{\bar{X}} U_{i}\right)$
Using (2.13) in (2.10)a, we get (2.10)b. Replacing $X$ by $\bar{X}$ in (2.9), we get
$-u^{j}\left(D_{\bar{X}} U_{i}\right)=\sigma(\bar{X})+\left(D_{U_{i}} u^{j}\right)(\bar{X})$

Using (2.14) in (2.10)a, we get(2.10)c.

## Theorem 2.4

$\ln V_{n}$, we have
$\overline{K(X, Y, \bar{Z})}=b^{2} K(X, Y, Z)+c u^{i}(K(X, Y, Z)) U_{i}$
(2.16) a
$p_{i}^{j} u^{i}(K(X, Y, \bar{Z}))=b^{2} u^{j}(K(X, Y, Z))+\left({ }^{(2)} p_{i}^{j}-b^{2} \delta_{i}^{j}\right) u^{i}(K(X, Y, Z))$
and

$$
\begin{array}{r}
b^{2}[K(\bar{X}, \bar{Y}, Z)+K(\bar{Y}, \bar{Z}, X)+K(\bar{Z}, \bar{X}, Y)] \\
=-c\left[u^{i}(Z) K\left(\bar{X}, \bar{Y}, U_{i}\right)+u^{i}(X) K\left(\bar{Y}, \bar{Z}, U_{i}\right)+u^{i}(Y) K\left(\bar{Z}, \bar{X}, U_{i}\right)\right] \tag{2.16}
\end{array}
$$

## Proof

Replacing $Z$ by $\bar{Z}$ in (1.18) and using (2.1)b, we get

$$
\begin{equation*}
K(X, Y, \bar{Z})=\overline{K(X, Y, Z)} \tag{2.17}
\end{equation*}
$$

Operating $F$ in (2.17) and using (1.1), we obtain (2.16)a. Operating $u^{j}$ on both sides of (2.16)a and using (1.5) and (1.6), we get(2.16)b. Bianchi's first identity of symmetric connexion $D$ is given by

$$
\begin{equation*}
K(X, Y, Z)+K(Y, Z, X)+K(Z, X, Y)=0 \tag{2.18}
\end{equation*}
$$

Operating F in (2.18), we get
$\overline{K(X, Y, Z)}+\overline{K(Y, Z, X)}+\overline{K(Z, X, Y)}=0$
Using (2.17) in (2.19), we get
$K(X, Y, \bar{Z})+K(Y, Z, \bar{X})+K(Z, X, \bar{Y})=0$
Replacing X by $\bar{X}, \mathrm{Y}$ by $\bar{Y}$ \& Z by $\bar{Z}$ in (2.20) and using (1.1), we get (2.16)c.

Affine connexion $D$ : Let us consider in $V_{n}$ an affine connexion $\tilde{D}$ satisfying

$$
\begin{equation*}
u^{i}(Y)\left(\tilde{D}_{X} U_{i}\right)+\left(\tilde{D}_{X} u^{i}\right)(Y) U_{i}=0 \tag{3.1}
\end{equation*}
$$

## Theorem 3.1

In $V_{n}$, we have

$$
\begin{equation*}
u^{i}(Y)\left[b^{2}\left(\tilde{D_{X}} U_{i}\right)+c u^{j}\left(\tilde{D_{X}} U_{i}\right) U_{j}\right]+\left(\tilde{D_{X}} u^{i}\right)(Y) p_{i}^{j} p_{j}^{k} U_{k}=0 \tag{3.2}
\end{equation*}
$$

$\left({ }^{(2)} p^{j}-b^{2} \delta_{i}^{j}\right) \operatorname{div} U_{j}=c u^{j}\left(\tilde{D_{U_{j}}} U_{i}\right)$ (3.2)b
Where
$\operatorname{div} \mathrm{X} \stackrel{\operatorname{def}}{=}\left(C_{1}^{1} \nabla X\right)$
(3.3) and
$(\nabla X) Y \stackrel{\text { def }}{=}\left(\tilde{D}_{Y} X\right)$

## Proof

Operating $F^{2}$ in (3.1) and using (1.1) and (1.2), we get (3.2)a. Now contracting (3.1) with respect to $X$ and using (3.3) and (3.4), we get
$u^{i}(Y) \operatorname{div} U_{i}+\left(D_{U_{i}} u^{i}\right)(Y)=0$

Replacing $i$ by j , then Y by $U_{i}$ in (3.3) and using (1.6), we get (3.2)b.

## Theorem 3.2

$\ln V_{n}$, we have
$c u^{i}(Y) u^{j}\left(\tilde{D}_{X} U_{i}\right)+\left({ }^{(2)} p_{i}^{j}-b^{2} \delta_{i}^{j}\right)\left(\tilde{D_{X}} u^{i}\right)(Y)=0$ (3.6) a $\left({ }^{(2)} p_{i}^{j}-b^{2} \delta_{i}^{j}\right)\left(\tilde{D}_{X} u^{i}\right)(Y) u^{j}\left(\tilde{D}_{Z} U_{i}\right)=c u^{i}(Y) u^{j}\left(\tilde{D}_{Z} U_{j}\right)\left(\tilde{D_{X}} u^{j}\right)\left(U_{j}\right)$

## Proof

By operating $u^{j}$ on (3.1) and using (1.6), we obtain (3.6)a.

Multiplying (3.2) ${ }_{c}$ with $u^{j}\left(D_{Z} U_{j}\right)$, we get (3.2)d.

## Affine connexion $\stackrel{\circ}{D}$

Let us consider in $V_{n}$ an affine connexion $\quad \stackrel{\circ}{D}$ satisfying

$$
\begin{equation*}
u^{i}(Y)\left({\stackrel{\mathrm{o}}{D_{X}}}^{U_{i}}\right)+\left(\stackrel{\mathrm{o}}{D_{X}} u^{i}\right)(Y) U_{i}=0 \tag{4.1}
\end{equation*}
$$

And

$$
\begin{equation*}
\left(\stackrel{\circ}{D}_{X} F\right)(Y)+\left(\stackrel{\circ}{D}_{Y} F\right)(X)=0 \tag{4.1}
\end{equation*}
$$

It may be noted that all the results of the section above hold for $\stackrel{\circ}{D}$. In addition we have the following results:

## Theorem 4.1

In $V_{n}$, we have


$$
\begin{equation*}
\stackrel{\circ}{D}_{\bar{Y}} \bar{X}-b^{2}\left(\stackrel{\circ}{D}_{Y} X\right)=\overline{\stackrel{\circ}{D}_{\bar{Y}} X}-\overline{\stackrel{\circ}{D}_{Y} \bar{X}}+c u^{i}\left(\stackrel{\circ}{D}_{Y} X\right) U_{i} \tag{4.2}
\end{equation*}
$$

And
$\stackrel{\circ}{D_{\bar{Y}}} \bar{X}+b^{2}\left(\stackrel{\circ}{D}_{Y} \bar{X}-\stackrel{\stackrel{\circ}{D}_{Y} X}{ }-\stackrel{\circ}{D_{\bar{Y}}} X\right)=c\left[\left\{u^{i}\left(\stackrel{\circ}{D_{\bar{Y}}} X\right)-u^{i}\left(\stackrel{\circ}{D}_{Y} \bar{X}\right)\right\} U_{i}+u^{i}\left(\stackrel{\circ}{D}_{Y} X\right) \overline{U_{i}}\right]$

## Proof

The equation (4.1)b is equivalent to
$\stackrel{\circ}{D}_{X} \bar{Y}+\stackrel{\circ}{D}_{Y} \bar{X}=\stackrel{\circ}{D}_{X} Y+\stackrel{\circ}{D}_{Y} X$

Operating $F$ in (4.3) and using (1.1), we get (4.2)a. Replacing $Y$ by $\bar{Y}$ in (4.3) and using (1.1), (4.3), we get (4.2)b. Further, Operating $F$ (4.2)b and using (1.1), we get (4.2)c.

## Affine connexion $D$ :

Let us consider in $V_{n}$ an affine connexion $D$ satisfying

$$
\begin{equation*}
u^{i}(Y)\left({\stackrel{*}{D_{X}}}^{*} U_{i}\right)+\left(D_{X}^{*} u^{i}\right)(Y) U_{i}=0 \tag{5.1}
\end{equation*}
$$

And

$$
\begin{equation*}
\left(\stackrel{*}{D}_{X} F\right)(Y)+\left(\stackrel{*}{D}_{\bar{X}} F\right)(\bar{Y})=0 \tag{5.1}
\end{equation*}
$$

It may be noted that all the results of the section three hold for $\stackrel{*}{D}$. In addition we have the following results:

## Theorem 5.1

$\ln V_{n}$, we have

$$
\begin{equation*}
\overline{D_{X} Y}+\stackrel{*}{D_{\bar{X}} \bar{Y}}-\stackrel{*}{D}_{X} \bar{Y}=b^{2}\left({ }^{*} \bar{X} Y\right)+c u^{i}\left({ }^{*} \bar{X} Y\right) U_{i} \tag{5.2}
\end{equation*}
$$

$\stackrel{*}{D}_{U_{j}} \bar{Y}+\left(\stackrel{*}{D}_{U_{j}} F\right) \bar{Y}=b^{2}\left(\stackrel{*}{D}_{U_{j}} Y\right)+c u^{i}\left({ }^{*} D_{U_{j}} Y\right) U_{i}$

Proof
(5.1)b is equivalent to

Using (1.1) in (5.3), we get (5.2)a. Replacing $X$ by $U_{i}$ in (5.3), we get

$$
\begin{equation*}
\left({\stackrel{*}{D_{U_{i}}}}^{\bar{Y}}-\overline{D_{U_{i}} Y}\right)+p_{i}^{j}\left[\stackrel{*}{D}_{U_{j}}\left(b^{2} Y+c u^{i}(Y) U_{i}\right]=p_{i}^{j}\left(\overline{D_{U_{j}} \bar{Y}}\right)\right. \tag{5.4}
\end{equation*}
$$

Replacing X by $U_{i}$ in (5.2)b, we get

$$
\begin{equation*}
\left(D_{U_{i}} \bar{Y}-\stackrel{*}{D_{U_{i}} Y}\right)=-p_{i}^{j}\left({ }^{*} D_{U_{i}} F\right) \bar{Y} \tag{5.5}
\end{equation*}
$$

From (5.4) and (5.5), we get

$$
\begin{equation*}
-p_{i}^{j}\left(D_{U_{i}} F\right) \bar{Y}+p_{i}^{j}\left[D_{U_{j}}\left(b^{2} Y+c u^{i}(Y) U_{i}\right]=p_{i}^{j}\left({\stackrel{*}{D_{U_{j}}} \bar{Y}}_{)}\right.\right. \tag{5.6}
\end{equation*}
$$

Using (5.1)a in (5.6), we get (5.1)b.

## Theorem 5.2

In $V_{n}$, we have
$\stackrel{*}{D}_{\bar{X}} \bar{Y}-b^{2}\left(\stackrel{*}{D_{X}} \bar{Y}\right)+b^{4}\left(\stackrel{*}{D}_{X} Y\right)=$


## Proof

Replacing $X$ by $\bar{X}$ in (5.3) and using (1.1), (5.1), we get (5.7).

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