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Effects of induced magnetic field and slip condition on peristaltic transport with heat and mass transfer in a non-uniform channel

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We study the effects of induced magnetic field and slip on the peristaltic flow of Jeffrey fluid in a nonuniform channel. Flow analysis is discussed in the presence of heat and mass transfer. Main emphasis is given to the study of stream function, the longitudinal pressure gradient, the magnetic force function, the axial induced magnetic field, the current density, the temperature and concentration. Numerical integration is carried out for pressure rise per wavelength. The flow quantities of interest are discussed by graphical illustrations.

Key words: Jeffrey fluid, induced magnetic field, slip, heat and mass transfer.

INTRODUCTION

The study of peristaltic flow is of special interest for several applications in industry and physiology. Especially the peristaltic transport of non-Newtonian fluids (Ellahi, 2009) is a topic of major interest of the researchers in the physiological world. Such interest is stimulated because of its occurrence in several physiological processes including chyme movement in the gastrointestinal tract, urine transport from kidney to bladder, movement of ovum in the female fallopian tube, transport of spermatozoa in the ductus efferentes of the male reproductive tract, transport of bile in bile duct, in roller and finger pumps, in vasomotion of small blood vessels and many others. It is now a well accepted fact that the peristaltic flows of magnetohydrodynamic (MHD) fluids are important in medical sciences and bioengineering. The MHD characteristics are useful in the development of magnetic devices, cancer tumor treatment, hyperthermia and blood reduction during surgeries. Hence several scientists having in mind such

importance extensively discussed the peristalsis with magnetic field effects (Reddy and Raju, 2010; Tripathi, 2011; Hayat et al., 2011a; Abd elmaboud and Mekheimer, 2011; Hayat et al., 2010a). Further, Singh and Rathee (2010, 2011) discussed the blood flow in the presence of an applied magnetic field. The pulsatile blood flow in the presence of applied magnetic field and body acceleration is examined by Sanyal et al. (2007). It is noticed that although ample literature on MHD peristaltic flow in the presence of applied magnetic field is available, very little attention is paid to the influence of induced magnetic field in peristalsis (Hayat et al., 2008a, b; Hayat et al., 2011b; Kotkandapani and Srinivas, 2008; Ali et al., 2008). In continuation, the induced magnetic field effect on the peristaltic motion in couple stress and micropolar fluids is addressed by Mekheimer (2008a, b). Hayat et al. (2010b, c) extended such discussion to third order and Carreau fluids. Abd elamboud (2011) examined induced magnetic field effect on peristaltic flow in an annulus.

The goal of the present study is to discuss the effect of induced magnetic field on peristaltic flow of Jeffrey fluid in non-uniform channel. The heat transfer and slip effects are also considered. The heat transfer analysis in such

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flow is important because of hemodialysis and oxygenation process. Further, there is always small amount of slippage in the real systems. Two different types of fluids exhibit slip effect. One case consists of fluids with very elastic properties and other rarefied gases. The slip effect appears in concentrated polymer solutions, molten polymers and non-Newtonian fluids. In the flow of dilute suspensions of particle, a clear layer is noticed next to a wall. Poiseuille observed such a layer using a microscope in the flow of blood through capillary vessels (Coleman et al., 1966). Few very recent contributions dealing with peristaltic flows subject to slip and heat transfer effects may be mentioned in the researches (Hayat et al., 2010d; Srinivas et al., 2009; Nadeem and Akram, 2010; Akbar et al., 2011).

ANALYSIS

We consider the MHD peristaltic flow of an incompressible Jeffrey fluid in a symmetric but non-uniform channel. The fluid is electrically conducting in the presence of constant magnetic field with strength Ho applied normal to the flow. This gives rise to an induced magnetic field $H'(h'_{X'}(X',Y',t'),h'_{Y'}(X',Y',t'),0)$ and ultimately the total magnetic field $H'^+(h'_{X'}(X',Y',t'),H'_0+h'_{Y'}(X',Y',t'),0)$. The flow generation is possible because of travelling wave on the channel walls.

The relevant equations for the present flow problem are given by:

$$\nabla \cdot \mathbf{H}' = \mathbf{0}, \quad \nabla \cdot \mathbf{\epsilon}' = \mathbf{0}, \quad \nabla \times \mathbf{\epsilon}' = -\mu_{\varepsilon} \frac{\partial \mathbf{H}'}{\partial \mathbf{t}'}, \quad (1)$$

$$\nabla \times \mathbf{H}' = \mathbf{J}', \quad \mathbf{J}' = \boldsymbol{\sigma} \{ \mathbf{\epsilon}' + \mu_{\varepsilon} (\mathbf{V}' \times \mathbf{H}'^{+}) \}, \quad (2)$$

$$\nabla \cdot \overline{\mathbf{V}}' = \mathbf{0}, \quad (3)$$

$$\rho \left[\frac{\partial}{\partial \mathbf{t}}' + (\mathbf{V}' \cdot \nabla) \right] \overline{\mathbf{V}}' = div \mathbf{T} - \mu_{\varepsilon} \left\{ (\mathbf{H}'^{+} \cdot \nabla) - \frac{1}{2} (\mathbf{H}'^{+})^{2} \nabla \right\}, \quad (4)$$

$$\rho C_p \frac{dT}{dt} = \kappa \nabla^2 T' + T.L, \qquad (5)$$

with L = gradV' and Cauchy stress tensor (T) and extra stress tensor (s) in Jeffrey fluid are

$$T = -p'\bar{I} + \mathbf{S}' \tag{6}$$

$$\mathbf{S}' = \frac{\mu}{1+\lambda_1} \left(\dot{\gamma} + \lambda_2 \ddot{\gamma} \right). \tag{7}$$

In the aforementioned expressions, p' denotes the pressure, f the

current density, \boldsymbol{I} the identity tensor, $\boldsymbol{\mu_e}$ the magnetic permeability, ρ the fluid density, σ the electrical conductivity, ϵ' an induced magnetic field, C_v the specific heat at a constant volume, κ the thermal conductivity, T the temperature, μ the dynamic viscosity of fluid, γ the shear rate, λ_1 the ratio of relaxation to retardation times, and λ_2 the retardation time and dots characterize material differentiation.

Induction equation in view of combination of Equations (1) and (2) becomes

$$\frac{\partial \mathbf{H}^{+}}{\partial t} = \nabla \times (\mathbf{V} \times \mathbf{H}^{+}) + \frac{1}{\xi} \nabla^{2} \mathbf{H}^{+}, \qquad (8)$$

where $\xi = 1/\mu\sigma$ is the magnetic diffusivity.

We perform the flow analysis in wave frame (x, y'). Hence the coordinates and velocities in the laboratory (X', Y') and wave (x', y') frames can be related through the following transformations:

$$x' = X' - ct', y' = Y', u'(x', y') = U' - c, v'(x', y') = V'$$
 (9)

where (U', V') and (u', v') are the respective velocities in the laboratory and wave frames.

The velocity V is chosen as follows:

$$\overline{V}' = (u', v', 0) \tag{10}$$

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Introducing the non-dimensional quantities .

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$$\begin{aligned} x &= \frac{x}{\lambda}, \quad y = \frac{y}{a}, \quad u = \frac{u}{c}, \quad v = \frac{v}{c}, \quad t = \frac{tc}{\lambda}, \quad p = \frac{a^2 p}{c\lambda\mu}, \quad S = \frac{aS}{\mu c}, \\ h &= \frac{h}{a}, \quad \Psi = \frac{\Psi}{ca}, \quad \Phi = \frac{\Phi}{H_0 a}, \quad \delta = \frac{\lambda}{a}, \quad R_g = \frac{\rho ca}{\mu}, \quad R_g = \sigma\mu_g ac, \\ S_1 &= \frac{H_0}{c} \sqrt{\frac{\mu_g}{\rho}}, \quad p_m = p + \frac{1}{2} R_g \delta \frac{\mu_g (H')^2}{\rho c^2}, \quad Br = E_r P_r, \quad \theta' = \frac{T - T_0}{T_1 - T_0}, \\ P_r &= \frac{\rho v C_p}{\kappa}, \quad E_r = \frac{c^2}{C_n (T_1 - T_0)}, \quad Sc = \frac{\mu}{\rho D}, \quad Sr = \frac{\rho T_0 D K_T}{\mu T_m C_0}, \end{aligned}$$
(11)

$$u = \frac{\partial \Psi}{\partial y}, \quad v = -\delta \frac{\partial \Psi}{\partial x}, \quad h_x = \frac{\partial \Phi}{\partial y}, \quad h_y = -\delta \frac{\partial \Phi}{\partial x}, \quad (12)$$

the incompressibility condition is satisfied whereas the other equations give

 $R_{e}\delta\left(\frac{\partial\Psi}{\partial y}\frac{\partial^{2}\Psi}{\partial x\partial y}-\frac{\partial\Psi}{\partial x}\frac{\partial^{2}\Psi}{\partial y^{2}}\right)=\\ -\frac{\partial p_{m}}{\partial x}+\delta\frac{\partial}{\partial x}(S_{xx})+\frac{\partial}{\partial y}\left(S_{xy}\right)+R_{e}S_{1}^{2}\frac{\partial^{2}\Phi}{\partial y^{2}}+R_{e}S_{1}^{2}\delta\left(\frac{\partial\Phi}{\partial y}\frac{\partial^{2}\Phi}{\partial x\partial y}-\frac{\partial\Phi}{\partial x}\frac{\partial\Phi}{\partial x}\right)$ $\frac{\partial \Phi}{\partial x} \frac{\partial^2 \Phi}{\partial y^2}$ (13)

$$R_{e}\delta^{3}\left(\frac{\partial\Psi}{\partial x}\frac{\partial^{2}\Psi}{\partial x\partial y}-\frac{\partial\Psi}{\partial y}\frac{\partial^{2}\Psi}{\partial x^{2}}\right) = -\frac{\partial p_{m}}{\partial y}+\delta^{2}\frac{\partial}{\partial x}\left(S_{yx}\right)+\delta\frac{\partial}{\partial y}\left(S_{yy}\right)-R_{e}\delta^{2}S_{1}^{2}\frac{\partial^{2}\Phi}{\partial x\partial y}-R_{e}S_{1}^{2}\delta^{3}\left(\frac{\partial\Phi}{\partial y}\frac{\partial^{2}\Phi}{\partial x^{2}}-\frac{\partial\Phi}{\partial x}\frac{\partial^{2}\Phi}{\partial x\partial y}\right),$$
(14)

 $\frac{\partial \Psi}{\partial y} - \delta \left(\frac{\partial \Psi}{\partial y} \frac{\partial \Phi}{\partial x} - \frac{\partial \Psi}{\partial x} \frac{\partial \Phi}{\partial y} \right) + \frac{1}{R_m} \left(\frac{\partial^2 \Phi}{\partial y^2} + \delta^2 \frac{\partial^2 \Phi}{\partial x^2} \right) = E,$ (15)

$$R_{g}\delta\left(\frac{\partial\Psi}{\partial y}\frac{\partial\theta}{\partial x} - \frac{\partial\Psi}{\partial x}\frac{\partial\theta}{\partial y}\right) = \frac{1}{P_{r}}\left(\delta^{2}\frac{\partial^{2}\theta}{\partial x^{2}} + \frac{\partial^{2}\theta}{\partial y^{2}}\right) + E_{r}\left\{\begin{array}{l}\delta S_{xx}\frac{\partial^{2}\Psi}{\partial x\partial y} + S_{xy}\\ \left(\frac{\partial^{2}\Psi}{\partial y^{2}} - \delta^{2}\frac{\partial^{2}\Psi}{\partial x^{2}}\right) - \delta S_{yy}\frac{\partial^{2}\Psi}{\partial y\partial x}\right\},\tag{16}$$

$$R_{g}\delta\left(\frac{\partial\Psi}{\partial y}\frac{\partial\varphi}{\partial x}-\frac{\partial\Psi}{\partial x}\frac{\partial\varphi}{\partial y}\right)=\frac{1}{Sc}\left(\delta^{2}\frac{\partial^{2}\varphi}{\partial x^{2}}+\frac{\partial^{2}\varphi}{\partial y^{2}}\right)+Sr\left(\delta^{2}\frac{\partial^{2}\varphi}{\partial x^{2}}+\frac{\partial^{2}\varphi}{\partial y^{2}}\right),$$
(17)

where Ψ , Φ , E_r , P_r , Sc, Sr, δ , R_e , R_m , and S_1 are respectively the stream function, magnetic force function, Eckert, Prandtl, Schmidt, Soret, wave, Reynolds, magnetic Reynolds and Strommer's numbers. Here p_m shows the total pressure which is sum of ordinary and magnetic pressures. Further, T_0, C_0 and T_1 , C_1 are the temperatures and concentrations at the upper and lower walls respectively and

$$\begin{split} S_{xx} &= \frac{2\delta}{1+\lambda_1} \left(1 + \frac{\lambda_2 c\delta}{d_1} \left(\frac{\partial \Psi}{\partial y} \frac{\partial}{\partial x} - \frac{\partial \Psi}{\partial x} \frac{\partial}{\partial y} \right) \right) \frac{\partial^2 \Psi}{\partial x \partial y'} \\ S_{xy} &= \frac{1}{1+\lambda_1} \left(1 + \frac{\lambda_2 c\delta}{d_1} \left(\frac{\partial \Psi}{\partial y} \frac{\partial}{\partial x} - \frac{\partial \Psi}{\partial x} \frac{\partial}{\partial y} \right) \right) \left(\frac{\partial^2 \Psi}{\partial y^2} - \delta^2 \frac{\partial^2 \Psi}{\partial x^2} \right), \\ S_{yy} &= -\frac{2\delta}{1+\lambda_1} \left(1 + \frac{\lambda_2 c\delta}{d_1} \left(\frac{\partial \Psi}{\partial y} \frac{\partial}{\partial x} - \frac{\partial \Psi}{\partial x} \frac{\partial}{\partial y} \right) \right) \frac{\partial^2 \Psi}{\partial x \partial y'}, \end{split}$$

with the boundary conditions given following

$$\Psi = 0, \quad \frac{\partial^2 \Psi}{\partial y^2} = 0, \quad \frac{\partial \Phi}{\partial y} = 0, \quad \frac{\partial \Phi}{\partial y} = 0, \quad \frac{\partial \Phi}{\partial y} = 0, \quad at \ y = 0,$$
(18)

$$\Psi = F, \ \frac{\partial \Psi}{\partial y} = -\beta S_{xy} - 1, \ \Phi = 1, \ \Theta' = 1, \ \varphi = 0, \ at \ y = h(x),$$
(19)

where the dimensionless slip parameter $\beta (= L/a)$.

In view of long wavelength and low Reynolds number analysis, one has from Equations (13) to (19) as

$$-\frac{\partial p}{\partial x} + \frac{\partial}{\partial y} \left(\frac{1}{1 + \lambda_1} \frac{\partial^2 \Psi}{\partial y^2} \right) + R_g S_1^2 \frac{\partial^2 \Phi}{\partial y^2} = 0,$$
(20)

$$-\frac{\partial p}{\partial y} = \mathbf{0},\tag{21}$$

$$\frac{\partial^2 \Phi}{\partial y^2} = R_m \left(E - \frac{\partial \Psi}{\partial y} \right). \tag{22}$$

Equations (21) and (22) after eliminating the pressure give

$$\frac{\partial^2}{\partial y^2} \left(\frac{1}{1+\lambda_1} \frac{\partial^2 \Psi}{\partial y^2} \right) + R_e S_1^2 \frac{\partial^8 \Phi}{\partial y^8} = 0.$$
⁽²³⁾

Now Equations (17) and (18) are presented in the forms

$$\frac{\partial^2 \theta}{\partial y^2} + Br\left\{\frac{1}{1+\lambda_1} \left(\frac{\partial^2 \Psi}{\partial y^2}\right)^2\right\} = 0, \tag{24}$$

$$\frac{1}{Sc}\frac{\partial^2 \varphi}{\partial y^2} + Sr\frac{\partial^2 \theta}{\partial y^2} = 0, \tag{25}$$

with the boundary conditions as follows

$$\Psi = 0, \quad \frac{\partial^2 \Psi}{\partial y^2} = 0, \quad \frac{\partial \Phi}{\partial y} = 0, \quad \frac{\partial \theta}{\partial y} = 0, \quad \frac{\partial \Phi}{\partial y} = 0, \quad at \ y = 0,$$
(26)

$$\Psi = F, \quad \frac{\partial \Psi}{\partial y} = -\frac{\beta}{1+\lambda_1} \frac{\partial^2 \Psi}{\partial y^2} - 1, \quad \Phi = 1, \quad \Theta' = 1, \quad \varphi = 0, \quad at \quad y = h(x).$$
(27)

Our interest in this study is to perform the analysis for the following wave forms.

(1) Sinusoidal wave $h(x) = 1 + Kx + \phi \sin(2\pi(x-t))$. (2) Triangular wave $h(x) = 1 + Kx + \phi \left[\frac{8}{\pi^5} \sum_{m=1}^{\infty} \frac{(-1)^{m+1}}{(2m-1)^2} \sin\{2(2m-1)\pi(x-t)\} \right].$ (3) Square wave $h(x) = 1 + Kx + \phi \left[\frac{4}{\pi} \sum_{m=1}^{\infty} \frac{(-1)^{m+1}}{(2m-1)} \cos\{2(2m-1)\pi(x-t)\}\right].$ (4) Trapezoidal wave $h(x) = 1 + Kx + \phi \left[\frac{\frac{32}{\pi^2} \sum_{m=1}^{\infty} \frac{(-1)^{m+1} \sin\left\{\frac{\pi}{s}(2m-1)\right\}}{(2m-1)^2} \sin\{2(2m-1)\pi(x-t)\} \right],$

with $\phi = b/a$ (amplitude ratio) and $K = \lambda k/a(k \ll 1)$. Total number of terms in the series that are incorporated in the analysis are 50. Note that the expressions for triangular, square and trapezoidal waves are derived from Fourier series.

The pressure rise per wavelength is

$$\Delta p_{\lambda} = \int_0^1 \frac{dp}{dx} dx. \tag{28}$$

EXACT SOLUTION

From Equations (20), (22) and (23) we have

$$\frac{\partial p}{\partial x} = \frac{\partial}{\partial y} \left(\frac{1}{1 + \lambda_1} \frac{\partial^2 \Psi}{\partial y^2} \right) + M^2 \left(E - \frac{\partial \Psi}{\partial y} \right), \tag{29}$$
$$\frac{\partial^4 \Psi}{\partial y^4} - (1 + \lambda_1) M^2 \frac{\partial^2 \Psi}{\partial y^2} = 0. \tag{30}$$

The aforementioned equations along with the corresponding boundary conditions give

$$\Psi = \frac{1}{L^2} \{ (\cosh(Ly) - \sinh(Ly)) (C_2 + C_1 \cosh(2Ly) + C_1 \sinh(2Ly)) \} + C_3 + C_4 y,$$
(31)

$$\frac{dp}{dx} = \frac{(C_1 - C_2)L}{(1 + \lambda_1)} - \frac{\{(C_1 - C_2)L + L^2(C_4 - E)\}}{L},$$
(32)

$$C_1 = -\frac{(F+h)(1+\lambda_1)L^2}{2L_1}, \quad C_2 = \frac{(F+h)(1+\lambda_1)L^2}{2L_1}, \quad C_3 = 0,$$

$$C_4 = \frac{FL(1+\lambda_1)\cosh(hL) + (1+F\beta L^2 + \lambda_1)\sinh(hL)}{L_1},$$

where $M^2 = R_m R_e S_1^2$ (is the Hartman number), $L = M \sqrt{(1 + \lambda_1)}$;

 $L_1 = hL(1 + \lambda_1)\cosh(hL) + (-1 + hL^2\beta - \lambda_1)\sinh(hL).$ The corresponding systems for Φ and θ after using Equation (31) finally give

$$\Phi = \frac{1}{2LM^2(1+\lambda_1)} (2L^3(C_5 - C_6y) - (L^3y^2(C_4 - E) + 2(C_1 - C_2)\cosh(Ly) + 2(C_1 + C_2)\sinh(Ly))R_m),$$
(33)

$$\theta' = -\frac{1}{4L^4} \left(-4 \left(-BrC_1 C_2 L^4 y^2 + L^4 (C_7 \mp y) \right) + Br(C_1^2 + C_2^2) L^2 \cosh(2Ly) + Br(C_1^2 - C_2^2) L^2 \sinh(2Ly) \right),$$
(34)

$$C_{5} = \frac{(hL(2(C_{1}+C_{2})+hL^{2}(C_{4}-E)+2(C_{1}-C_{2})\cosh(hL)+2(C_{1}+C_{2})\sinh(hL))R_{m}}{2L^{3}},$$

$$C_{6} = \frac{(C_{1}+C_{2})R_{m}}{L^{2}}, C_{8} = \frac{Br(C_{1}^{2}-C_{2}^{2})}{2L},$$

$$C_{7} = \frac{Br(2hL(-C_{1}^{2}+C_{2}^{2}+2C_{1}C_{2}hL)+(C_{1}^{2}+C_{2}^{2})\cosh(2hL)-(C_{1}^{2}-C_{2}^{2})\sinh(2hL))}{4L^{2}}$$

Now the results for axial induced magnetic field h_x , current density distribution J_z and concentration distribution φ are given by

$$h_{x} = \frac{C_{6}L^{2} - (L^{2}y + (C_{1} + C_{2})\cosh(Ly) + 2(C_{1} - C_{2})\sinh(Ly))R_{m}}{L^{2}},$$
(35)

$$\begin{split} J_{z} &= \frac{(2L^{s}(C_{4}-E)+2(C_{1}-C_{2})L^{2}\cosh(hL)+2(C_{1}+C_{2})L^{2}\sinh(Ly))R_{m}}{2L^{s}}, \end{split} (36) \\ & \varphi = \frac{1}{4L^{4}} (4(C_{9}L^{4}+y(BrC_{1}C_{2}L^{4}yScSr+C_{10}L^{4})) + Br(C_{1}^{2}+C_{2}^{2})ScSrL^{2}\cosh(2Ly) + Br(C_{1}^{2}-C_{2}^{2})ScSrL^{2}\sinh(2Ly)), \end{aligned} (37) \\ & C_{9} &= \frac{BrL^{2}ScSr(2hL(-C_{1}^{2}+C_{2}^{2}+2C_{1}C_{2}hL)+(C_{1}^{2}+C_{2}^{2})\cosh(2hL)+(C_{1}^{2}-C_{2}^{2})\sinh(2hL)}{2L^{4}}, \\ & C_{10} &= \frac{Br(C_{1}^{2}-C_{2}^{2})ScSr}{2L}, \end{split}$$

RESULTS AND DISCUSSION

In order to predict the effects of pertinent parameters on various quantities such as pressure rise per wavelength (Δp_{λ}) , the streamlines (Ψ), the axial induced magnetic field (h_x) , the current density distribution (J_z) , the temperature (θ') and concentration (ϕ) distributions, the Figures 1-7 are displayed for different wave forms. This analysis mainly focuses for the effects of slip parameter (β), Hartman number (M), the ratio of relaxation to retardation times (λ_1), Brinkman number (Br), Schmidt number (Sc) and Soret number (Sr).

Figures 1(a-d) characterize the pumping mechanism for different values of λ_1 . There are four types of regions regarding pumping. When the dimensionless mean flow rate (θ) and pressure rise per wavelength (Δp_{λ}) are positive it defines the peristaltic pumping region. For $\theta > 0$ and $\Delta p_{\lambda} < 0$, we have augmented pumping and for $\theta = 0$, $\Delta p_{\lambda} > 0$ is a free pumping region. One also has retrograde pumping when $\theta > 0$ and $\Delta p_{\lambda} < 0$. Figure 1a shows clearly that for sinusoidal wave, the Δp_{λ} increases for small values of λ_1 in retrograde pumping region whereas a reverse situation is noticed in the augmented region, that is Δp_{λ} increases by increasing λ_1 . The other wave forms also show the similar behavior as that of sinusoidal wave. It is also observed that Δp_{λ} is maximum for square wave and minimum for triangular wave. The variation of M on axial induced magnetic field (h_x) with y over a cross section x = 0.1 is displayed in the Figures 2(a-d). It is revealed from the Figure 2a that magnitude of axial induced magnetic field (h_x) increases for M. Interestingly, the axial induced magnetic field (h_{r}) in the upper half region is in one direction while



Figure 1. Plot for Δp_{λ} versus x. The other parameters are K = 0.005, $\phi = \frac{\pi}{6}$, E = 0.4, t = 0.1, $\beta = 0.2$, $R_e = R_m = S_1 = M = 1$.





3 and x = 0.1

it is in the opposite direction in the lower half region. Further, h_x is equal to zero at y = 0. These results also hold for all the other considered wave forms in Figure 2(c-d). A comparative study further indicates that h_x is maximum for square wave and minimum for trapezoidal wave. To see the variation of current density distribution (J_z) versus y over a cross section x = 0.1, we have plotted the Figures 3(a-d). Here we found that J_z is an increasing function

of M. Trapping is an interesting phenomenon in theory of peristaltic transport. The formation of an internally circulating bolus of the fluid by closed streamlines is called trapping and this trapped bolus is pushed ahead along the peristaltic wave with the speed of wave. Here Figures 4-5 have been



Figure 4a. Streamlines (sinusoidal wave) for $\lambda_1 = 0.5$, $\lambda_1 = 1.5$.



Figure 4b. Streamlines (triangular wave) for $\lambda_1 = 0.5$, $\lambda_1 = 1.5$.

plotted for the description of trapping when $M = 1, \beta = 0.03, \varphi = \frac{\pi}{6}, a = b = 0.4, d = 1.1$ and θ =0.61. The streamlines for different values of λ_1 are shown in Figure 4. It is noticed that the size of the trapped bolus decreases from $\lambda_1 = 0.5$ to $\lambda_1 = 1.5$. In Figure 5 we have sketched the streamlines for different values of M. This Figure depicts that trapping reduces

for large values of M. That is size of the trapped bolus is going to squeeze from hydrodynamic to magneto-hydrodynamic situations for all the considered wave forms.

In the Figures 6(a-d) and 7(a-d), the temperature and concentration profiles have been illustrated. As expected, the temperature is an increasing function of Br (Figure 7). In fact Brinkman number is a measure of the importance of viscous heating relative to the conductive heat transfer.



Figure 4c. Streamlines (square wave) for $\lambda_1 = 0.5$, $\lambda_1 = 1.5$.



Figure 4d. Streamlines (trapezoidal wave) for $\lambda_1 = 0.5$, $\lambda_1 = 1.5$.

An increase in the Brinkman number increases the energy in the molecules and consequently the temperature increases. Here it is also observed that the temperature profile looks almost parabolic. The temperature is maximum for the sinusoidal and trapezoidal waves.

The Schmidt number is defined as the ratio of momentum diffusivity and mass diffusivity and is used to characterize the fluid flows in which there are simultaneous



Figure 5a. Streamlines (sinusoidal wave) for M = 1, M = 2.



Figure 5b. Streamlines (triangular wave) for M = 1, M = 2.



Figure 5c. Streamlines (square wave) for M = 1, M = 2.



Figure 5d. Streamlines (trapezoidal wave) for $M=\,$ 1, $M=\,$ 2.



momentum and mass diffusion convection processes. Since Sc has a direct relation with mass diffusion rate therefore increases for small values of Sc. It is observed that such decrease is maximum for square wave form.

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b = 0.4, d = 1.1 and x = 0.1

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