Review

Seven-dimensional space-time and its objects: Arbitrary spin state, electromagnetic fields, mirror symmetry and superconductivity

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To form the basis spin states of a field, vector states of the multicomponent wave function to the four coordinates of Minkowski space that determine the position of the local observer have been added by angular extra dimensions that determine the orientation of the local observer. The generators of the Poincare group in the angular representation have been obtained. The Dirac equation (generalized for any spin) and Maxwell's equation have been designed from these generators. In the framework of transformations of the Lorentz group in angular representation united with its transpose representation, the transformations of the (generalized) Dirac equations that is similar to the Heaviside-Larmor transformations for Maxwell's equations have been performed. As a result, the Dirac equation for the Dirac monopole, which corresponds to a particle with mirror symmetry have been obtained. Indication of a low probability of the existence of the Dirac monopole had been obtained.

Key words: Spinor representation of the Poincare group, seven dimensions of space-time, mirror symmetry.

INTRODUCTION

Hidden harmony is stronger than the explicit one. Heraclitus Space-time and matter are inseparable from each other. Classical mechanics knows two classes of systems: "material points" and "rigid bodies". In building up a general mathematical theory applying to any system, one usually starts from the equations of motion of a material point. From a physical point of view, however, the idea of "rigid body" is as fundamental a conception as the idea of "material point" (Casimir, 1931). Quantum-mechanical theory of angular momentum of a rigid body has a strong position in the mathematical formalism of modern quantum physics (Bidenhander and Lauk, 1984; Varshalovich, 1975). This formalism includes the use of Wigner D functions dependent on Euler angles \( \varphi, \theta, \gamma \) determining the orientation of the local observer in relation to the ordinary meter. This formalism allows to determine the direction of a vector in space, the orientation of the local observer, addition of vectors, basis states with spin and their transformation properties under rotation through the functions of \( \varphi, \theta \) and \( \gamma \) at once for all points in space without reference to a specific point \( x_1, x_2, x_3, t \) but connected with the orientation of the meter.

In the space of orientations of the observer (of the rigid body) there exist Wigner D functions, for a half-integer
value of j which are transformed with using the group SU(2) instead of SO(3) when turn in the space of \(x_1, x_2, x_3\) and t takes place. In Minkowski space there do not exist objects whose *functions are transformed using the group SU(2)* (Sventkovsky, 2004).

Similar to the fact that the position of the particle is described by wave function depending on the \(x_1, x_2, x_3\), and t, the orientation of the particle (an electron is a point particle) also may be described by a wave function depending on its possible orientations \(\phi, \theta\) and \(\gamma\).

In this paper, the emphasis has been shifted from the consideration of transformations themselves to the objects of transformations. For this purpose, besides the ordinary coordinate system called the meter two local observers (ordinary and rotated) have been introduced in Minkowski space-time which have the center at the same point \(x_1, x_2\) and \(x_3\) related to the position of the particle field. The ordinary observers are parallel to the meter. The use of the ordinary local observer is due to the known position that a rotation of the meter in the neighborhood of \(x_1, x_2\) and \(x_3\) can be divided into two transformations. The translation of a point which does not change the angle variables and the rotation of the ordinary local observer around the point \(x_1, x_2\) and \(x_3\) in the coordinate system with center at the point \(x_1, x_2\) and \(x_3\) by the same angle.

The transformation properties of the spin state under rotation of the meter are offered to describe identically under rotation of the rotated local observer.

Interpretation of the well-known principle of superposition (spin) states for multicomponent wave functions as the principle of superposition of states for any fixed direction at every point was the basis for the introduction of new angular dimensions for the wave function.

A multicomponent wave function describing vector fields, particles with spin in Murkowski space, is propose equivalently interpreted as the presence of an internal rotational degree of freedom (field) at each local point that are not related to the spatial variables. Angular extra dimensions \(\phi, \theta\) and \(\gamma\) have been introduced in Sventkovsky (2004), but a number of important provisions of the theory are not expressed or are expressed only partly. In Portnov (2011), there is a discussion of the use of these variables in the development of general relativity theory, but not at the quantum level.

The physical foundations for the introduction of extra dimensions for explaining the nature of multicomponent wave function with known Lorentz transformation properties of states with spin, intrinsic parity as an internal degrees of freedom of the fields are discussed in the article.

Symmetry of the equations of quantum mechanics and Maxwell equations has a higher order than the symmetry associated only with the group of Lorentz. A generalized Lorentz group corresponding to the unification of the Lorentz group in the matrix (spinor, vector) representation and its transpose representation has been obtained in Sventkovsky (2004) for any j in operator form. The group of internal symmetry is considered as a sub-group of the generalized Lorentz group and corresponds to the transition from one type of particles, fields and representations to another.

The equivalence between the Schrodinger operator equation and Heisenberg’s matrix mechanics was proved in 1927 for operators dependent on the time-space coordinates (Teschl, 2009). A similar construction (substitution of matrices by operators) concerned only with the operators acting on the angular variables which are introduced to explain the nature of spinors and vector fields is considered in the present paper. The relationship between Dirac matrices, the equations of Maxwell and generators of the generalized Lorentz group is also studied in the article.

**TWO INTERNAL LOCAL OBSERVERS WITH THE CENTER AT ONE POINT**

The meter is the original right Cartesian coordinate system. At the center of the point \(x_1, x_2\) and \(x_3\) original local observer with unit vectors \(X_1, X_2\) and \(X_3\) parallel to the meter were introduced. For describing objects with zero size at the center of the point \(x_1, x_2\) and \(x_3\) a rotated local observer with unit vectors \(X^{(1)}, X^{(2)}\) and \(X^{(3)}\) and with the orientation defined by three independent Euler angles \(\phi, \theta\), \(\phi^, \theta\) and \(\gamma\) with respect to the local original observer were introduced as shown in Figure 1. In fact, instead of one rotated observer are introduced a lot of rotated observers \(\phi, \theta\) and \(\gamma\). Turning one rotated observer means turning a lot of the multidirectional rotated observers.

The superscript and the subscript in operators \(X^{(k)}, J_{(k)}\), \(J_{(k)}\) refer to respectively the rotated observer with unit vector \(X^{(k)}\) and to the ordinary observer with unit vector \(X\). The rotation matrix can be written in a symmetrical form with respect to the two local observers (Bidenhander and Lauk, 1984):

\[
R_{ij} = (X^{(1)}X^{(2)}X^{(3)}) = R(X_1, X_2, X_3) = R_3(\phi) R_2(\theta) R_3(\gamma),
\]

\[
X^{(1)} = -\sin(\theta) \sin(\gamma) + \cos(\theta) \cos(\phi) \cos(\gamma), X^{(2)} = \sin(\theta) \sin(\gamma), X^{(3)} = \sin(\theta) \cos(\phi) \cos(\gamma),
\]

\[
X^{(1)} = -\sin(\phi) \sin(\gamma) - \cos(\phi) \cos(\theta) \sin(\gamma), X^{(2)} = \sin(\phi) \sin(\gamma), X^{(3)} = \sin(\phi) \cos(\theta) \sin(\gamma),
\]

\[
X^{(1)} = \cos(\phi) \cos(\gamma) - \cos(\phi) \cos(\gamma) \sin(\phi) \cos(\gamma), X^{(2)} = \sin(\phi) \cos(\theta) \sin(\gamma), X^{(3)} = \sin(\phi) \cos(\theta) \cos(\gamma), X^{(3)} = \sin(\phi) \cos(\theta),
\]

The generators of the rotation group \(J_k\) or angular momentum operators of rigid body will be called the generators of the vector rotations relative to the original local observer. The projections \(J_k\) onto the axis of the rotated local observer: \(J^{(k)} = (X^{(k)}J)\) are considered in literature as the operators of the angular momentum of a symmetric top. Let \(\epsilon_{123}\) is the antisymmetric tensor \(\epsilon_{1,2,3}=1\).
The orientation of the rotated local observer with respect to the original local observer.

\[ J_1 = i \cos(\varphi) \frac{\partial}{\partial \varphi} + i \sin(\varphi) \frac{\partial}{\partial \theta} - i \cos(\varphi) \frac{\partial}{\partial \varphi}, \]
\[ J_2 = i \sin(\varphi) \frac{\partial}{\partial \varphi} - i \cos(\varphi) \frac{\partial}{\partial \theta} + i \cos(\varphi) \sin(\theta) \frac{\partial}{\partial \varphi}, \]
\[ J_3 = -i \frac{\partial}{\partial \varphi}, \]
\[ [J_i, J_j] = i \varepsilon_{ijk} J_k, [J_0, J_i] = -i \varepsilon_{ijk} J_k, [J_i, J_j] = 0 \quad (1) \]

The operators \( J^{(n)} \) are generators of the transposed rotation group. They are also generators of a group of rotations of the rotated local observer \( X^{(1)}X^{(2)}X^{(3)} \) relative to itself. It is impossible to interpret the rotation by means of operators \( J_0 \) by the rotation by means of operators \( J^{(n)} \), as the operator \( J_0 \) cannot be obtained from \( J^{(n)} \) by using a unitary similarity transformation (Bidenhander and Lauk, 1984). The operators \( J_0 = X^{(0)} \).

Vectors in coordinate system \( X^{(k)} \) will be called isovectors and rotation using \( J^{(n)} \) will be called rotation in the isovectors space.

Wigner D functions, \( D^{(m,m')}_{nm} \), are the eigenfunctions of the angular momentum operators \( J_3, J^{(0)}, J^{(2)} \). They correspond to the symmetry between the original observer and rotated observer and so it is written in this form:

\[ D^{(1/2)} = (\zeta^{(1/2)}, \zeta^{(1/2)}), \quad \zeta^{(1/2)} = (\psi_1, \psi_2), \quad \zeta^{(-1/2)} = (\psi_3, \psi_4), \]
\[ \psi_1 = \cos(\theta/2) \exp(i\gamma/2+i\varphi/2), \]
\[ \psi_2 = \sin(\theta/2) \exp(-i\gamma/2-i\varphi/2), \]
\[ \psi_3 = \sin(\theta/2) \exp(-i\gamma/2+i\varphi/2), \]
\[ \psi_4 = \cos(\theta/2) \exp(i\gamma/2-i\varphi/2) \quad (2) \]

The known symmetry operator between the original local observer and the rotated local observer has the form \( W \); \( \psi' = \gamma, \theta' = \theta, \gamma' = \varphi \) (Bidenhander and Lauk, 1984) and formally implements permutation by the places of these observers. The operator \( W \) corresponds to the operation of transposition for the representation of a rotation group which is denoted by icon \( ^T \). The icon \( ^\dagger \) is the operation of complex conjugation.

For example:

\[ J^{(k)} = (-1)^{k+1} W J_k, W D^{(T)} = X^{(k)}_n = (-1)^{k+n} W X^{(n)}_k. \quad (3) \]

The Euler angles \( \varphi, \theta, \gamma \) that determine the orientation of the local rotated observer relatively to the meter were named as extra dimensions to the four coordinates of the Minkowski space.

The elements of the new space \( \varphi, \theta, \gamma \) are Wigner D functions, \( D^{(m,m')} \) which are transformed using the group SU(2). The double space of all possible orientations for the rotated observer corresponds to the space domain of the angles Wigner D functions with volume \( \int d\Omega d\varphi = 16 \pi^2 \).

Vectors \( \xi^{(m)}(\varphi, \theta, \gamma) \) and \( \xi^{(m')}(\varphi', \theta', \gamma') \) are obtained using the group SU(2).

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The elements of the new space \( \varphi, \theta, \gamma \) are Wigner D functions, \( D^{(m,m')} \). These functions are bases of orthogonal functions:

\[ <\xi^{(m)}, \xi^{(n)}> = \delta_{mn} \delta_{m+n}/b^2 \]

where \( b = \sqrt{(2j+1)/(4\pi)} \). Icons are used only for the orientations space, and \( \delta_{mn} \) is the Kronecker delta, \( \delta_{mn} = 1 \).

Any column \( \xi^{(m)} \) of the matrix \( D^{(m,m')} \) is transformed in the same manner as a spinor \( j \) under spatial rotation and corresponds to a complete set of basis vectors describing states with spin \( j \) (Varshalovich, 1975), as \( J^{(m,m')} = \xi^{(m)} S, [S, S]\xi = i \varepsilon_{ijk} S, S \) is the matrix operator of angular momentum.

The rotated observer for state \( j \) also as original observer has \( 2j+1 \) degrees of freedom corresponding to the analog of the spin projections \( m' = -j, ..., +j \),

\[ J^{(3)} \xi^{(m)} = m' \xi^{(m)} \]

For example \( j = 1/2, 2S = \sigma_0 \) are Pauli matrices. Let \( \xi_0 \) be any m string of the matrix \( D^{(m,m')} \). Using the operator \( W \), the identities were obtained:
J⁰⁺ξ⁰_m=ξ_mS_k^T, J_k=∑(-1)^k⁺S_k, ξ_m=Wξ^{m(T)},
J_j=J⁽⁽1⁾⁺J⁽⁽2⁾⁻ξ_j^m(m)=(j⁻m')(j+m'⁺1) ξ_j

Taking into account the completeness of the system of bases Dₖ, any spinor j, ψ⁽⁽1⁾=ψ⁽⁽1⁾, ψ⁽⁽2⁾,..., ψ⁽⁽j⁾ can be represented as a linear combination of the spinors j, which depend only on ϕ, θ and γ (Bidenhander and Lauk, 1984).

The transformation using exponential operator is taken using the Baker-Campbell-Hausdorff formula:


The presence of well-known transformational properties of these bases of spinors ξ⁽⁽m⁾, vectors X⁽⁽m⁾, (Bidenhander and Lauk, 1984) is based on the premise that the bases themselves are represented as the rotation matrix D⁽⁽1⁾, (R) under the turn of the original local observer onto Euler angles α, β and c.

D⁽⁽φ',θ',γ')⁽⁽1⁾=D⁽⁽φ,θ,γ⁾⁽⁽1⁾D⁽⁽α,β,c⁾=(exp(-icJ₃)exp(-iβJ₂)exp(-iωJ₃))D⁽⁽φ,θ,γ⁾⁽⁽1⁾,

D⁽⁽α,β,c⁾=exp(-icS₃)exp(-iβS₂)exp(-icS₃).

The rotations of the original local observer (Equation 4) and the rotated local observer onto angles ω are also realized by the rotation operators exp(-iωJ₃) and exp(-iωJ⁽⁽0⁾). We have identities:

exp(-iωJ₃)(X⁽⁽p⁾,X⁽⁽q⁾,X⁽⁽r⁾)=(X⁽⁽p⁾,X⁽⁽q⁾,X⁽⁽r⁾)R₃(ω),
exp(-iωJ⁽⁽0⁾)=X⁽⁽1⁾,X⁽⁽2⁾,X⁽⁽3⁾)=X⁽⁽1⁾,X⁽⁽2⁾,X⁽⁽3⁾)R₃(ω),

The known spatial transformation and Lorentz transformation can be obtained in two equivalent ways, both with the help of generators of the Lorentz groups and with the help of the transformation of angles ϕ, θ and γ which correspond to the transformations of the vectors X⁽⁽1⁾, X⁽⁽2⁾ and X⁽⁽3⁾. For example, rotating the meter around the X₃ axis by an angle α is accompanied by a transformation of the angle ϕ'=ϕ-α, hence ξ⁽⁽11/2⁾)=exp(-icα/2)ξ⁽⁽11/2⁾) is gotten.

Assuming that the spinors ξ⁽⁽11/2⁾) are a Weyl spinors which has the known Lorentz transformation with velocity, v=||V|=Vc, th(x)=Vc, ξ⁽⁽11/2⁾)=exp(2m x)ξ⁽⁽11/2⁾) and taking into account the symmetry by angle θ, the following angular transformation were obtained: Ψ⁽⁽1⁾=Ψ⁽⁽1⁾, Ψ⁽⁽2⁾=Ψ⁽⁽2⁾, Ψ⁽⁽3⁾=Ψ⁽⁽3⁾, Ψ⁽⁽0⁾=Ψ⁽⁽0⁾, Ψ⁽⁽1⁾=Ψ⁽⁽1⁾, Ψ⁽⁽2⁾=Ψ⁽⁽2⁾, Ψ⁽⁽3⁾=Ψ⁽⁽3⁾, Ψ⁽⁽n⁾=Ψ⁽⁽n⁾, Jₖ,Jₖ⁺1, Jₖ⁺2, Jₖ⁺3=Ψ⁽⁽n⁾, Jₖ,Jₖ⁺1, Jₖ⁺2, Jₖ⁺3.

That the Lorentz transformation-X⁽⁽3⁾, X⁽⁽0⁾ and x₃, t is realized in the same way as a four-dimensional vector x, t and X⁽⁽3⁾, X⁽⁽0⁾ has a length of zero was obtained. Also that X⁽⁽1⁾, X⁽⁽2⁾ are transformed as bivector E and H of the electromagnetic field X⁽⁽1⁾, X⁽⁽2⁾, X⁽⁽3⁾ was obtained. For a unified description of states with spin j, vector and tensor fields dependent on the orientation of the meter, we introduce the state of a class 2j, as a class of functions Ψ=ψ C which may be represented by a homogeneous polynomial of degree 2j of ψₖ, (2) (Varshalovich, 1975). This class corresponds to the principle of superposition of states. For example, the Wigner D function, D⁽⁽1⁾ has a class 2j. The Lorentz transformation does not change the class 2j of functions Ψ since ψ⁽⁽k⁾, (2), j=1/2 are linearly transformed.

The introduction of the state of the class 2j is also associated with the expansion of the description of spinors j under the Lorentz transformation and is also connected with the overcoming of the difficulties associated with the ambiguity of the transformations of the wave function from the angular variables and which is also of the analogous difficulties described in Cartan (1927) under the matrix interpretation.

Example, under the Lorentz transformation of spinor j or D⁽⁽1⁾ may appear additional summands (components) in the form spinor j-1, j-2 or X⁽⁽0⁾, X⁽⁽1⁾, X⁽⁽2⁾, X⁽⁽3⁾ which can be verified. Any spinor j can be expanded in the identical ladder form that does not change the class 2j, as a class of functions Ψ=ψ C which may be represented by a homogeneous polynomial of degree 2j of ψₖ, (2).

The states with spin 1/2 has the next unique property: In the summation of states ψ₁, ψ₂ or ψ₃, C⁽⁽11/2⁾, Ψ=ψ₁+Cψ₂+Cψ₃ that corresponded to different orientations of spin, there is always such a rotated coordinate system X⁽⁽m⁾=Cₖ, X⁽⁽m⁾, C⁽⁽11/2⁾) in which the spin is described by C⁽⁽11/2⁾, and Ψ has the same form Ψ=ψ₁. There are only two independent forms (functions) ψ₁ and ψ₂ except for their linear combination, where ψ₁=ψ₂. This property will be named to the property unchangeability of form of the angular function when similar states are added.

A multicomponent wave function C⁽⁽11/2⁾, C⁽⁽11/2⁾, C⁽⁽11/2⁾, C⁽⁽11/2⁾)=Cₑ | k > corresponding to the spin (vector) states in the isotropic Minkowski space is proposed equivalently (one to one) to describe as a one-component wave function Cₑ=ψₑ space, where |k>=|0, 0, 1, 0, 0, 0) is unit basis, Cₑ depends only on x₁, x₂, x₃, t and ψₑ depends only on ϕ, θ and γ. This corresponds to the replacement in the wave function of the matrix basis |k> by an operator basis ψₑ with the same transformation properties as for
the matrix basis using group SU(2). \( \phi, \theta \) and \( \gamma \) may be interpreted as the possible orientation of the particle. The decomposition of \( \Psi \) in the basis \( \psi_k \) corresponds to the multicomponent wave function \( C \).

\[
C_i = \langle \Psi | \psi_i \rangle, \quad J_3 \Psi_{m} = m \psi_{m}, \quad C^T C = \langle \Psi | \Psi \rangle, \quad <\psi_i | \psi_k > = \delta_{i k}.
\]

For the physical meter in Minkowski space angular dimensions are hidden, internal and not observable, that is, all physical quantities at each point of space are calculated as averaged values over double the space of all orientations.

The elements of the seven-dimensional space are the one-component wave functions \( \Psi = \psi C \).

Spatial transformation properties of spinors \( C \) are provided by the choice of \( \psi \) in the form of the spinor as any a linear combination of spinors \( \xi^{(m)}, j \) and Sommerfeld conditions, according to which the wave function \( \Psi = \psi C \) must be invariant under the Lorentz transformations \( \psi C = \psi'C \). Therefore, the transformation properties of basis \( \psi \) and \( C \) are related to each other, namely:

\[
\text{if } \psi^T = U \psi, \ C^T = V C \text{ then } U^T \psi = 1, \ V = (U^{-1})^T.
\]

The rotation matrices \( U \) and \( V \) are unitary matrices so \( V = U^* \). For \( \Psi = \psi C \) the vectors \( \psi = X^{(k)} \) and \( C \) have the same (identical) transformational properties as:

\[
U = R(\alpha, \beta, c)^{-1}, \ V = R^{-1}
\]

For the spinor we have:

\[
\psi^T = D' (\alpha, \beta, c) \psi, \ C' = D'(\alpha, \beta, c)^T C, \quad (\psi_1', \psi_2') = (\psi_1, \psi_2) \exp(-\text{i} \omega \sigma_n), \quad C' = \exp(\text{i} \omega \sigma_n) C,
\]

Lorenz transformation properties of spinor \( C \) are provided selecting \( \psi \) in the form specific of a linear combination of \( \xi^{(m)}, j \) which satisfy the famous Lorentz transformations of the spinor \( C \).

All dimensions \( x_1, x_2, x_3, t \) and \( \phi, \theta, \gamma \) are mutually independent, but their transformational properties, except translation, are interconnected. The transformation properties of fields (vector, spin, etc.), except translation, are fully described the transformation properties of the basis functions of \( \phi, \theta \) and \( \gamma \).

Note that a field is present only in \( C \), but \( \psi \) has no field, because \( \phi, \theta, \gamma \) have no relation to the coordinates \( x_1, x_2, x_3 \) and to the position of the local meter. The initial values \( \phi, \theta, \gamma \) (downward) are related only to the orientation of the generator. The group elements \( j^{(n)}, J_n, \partial \phi \partial t, \partial \phi \partial \theta, \partial \phi \partial \gamma \) act only on basis functions \( \psi \) in \( \Psi = \psi C \), but not on the field \( C \).

Each representation of spinors \( \xi^{(k)}, k = -j, j \), may have its own invariant \( \Psi_k = C^{(k)} \xi^{(k)} \) under spatial rotations. After completing the Lorentz transformation (Sventkovsky, 2004) for arbitrary spinor \( \xi^{(k)} \) which is a basis of spatial rotations, the full extended Lorenz basis \( j \) was gotten. Moreover, the extended components of the basis are also spinors corresponding \( j' = [-1, j, 2, ..., X^{(0)}(c)(d), X^{(0)}(n) \xi^{(n)} ...].\)

The wave function \( \Psi \) of the class \( 2j \) can be composed of \( 2j+1 \) independent Lorentz invariants \( \Psi^{(i)} = C^{(i)}(c) \xi^{(k)} + C^{(n)}(n) \xi^{(n)} \) obtained from \( 2j+1 \) invariants of \( C^{(i)}(c), k = -j, j' \) under spatial rotations, plus the invariant \( C^{(0)}(c) \xi^{(n)} \) obtained via extended Lorenz basis \( \xi^{(k)} \).

**Theorem 1**

A spatial inversion leads to internal inversion \( I \). \( \dot{r} = t, x_1 = -x_1; \ \dot{\psi} = \pi + \psi, \ \dot{t} = \pi - t, \ \dot{\theta} = \pi - \theta, \ \dot{\gamma} = \pi - \gamma \), which is an equivalent to the turn of the rotated local observer about axis \( X^{(2)} \) by angle-\( \pi \). This follows from the identities:

\[
\dot{\epsilon}^{(2)} = (-1)^T \dot{j} \dot{\epsilon}^{(2)}, \ F^{(2)}(2) = (-1)^2 \dot{\theta} \dot{\epsilon}^{(2)}, J_1 = \dot{J_1}, \dot{X}^{(2)} = (-1)^k X^{(2)}, I = \exp(\text{i} \pi J^{(2)}).
\]

The law of conservation of parity is directly related to the conservation of symmetry between the left and the right. The bases \( D_{(m', m''}) \) and \( D_{(m, m''}) \) are linked by inversion transformation \( I D_{(m', m''}) = (-1)^{m'} D_{(m, m'').} \)

This allows to divide the entire basis into two equal groups of basis, except the case \( m = 0 \) for the whole \( j \). The group of bases \( m' < 0 \) is called the left and its mirror \( m' < 0 \) is called the right. The difference (balance) between the left and the right, with weight \( m' \), is calculated as the average value of the operator \( J^{(3)} \). For example:

\[
\Psi = C^{(m)} D_{(m, m)} C_{(m', m''})^{*}, \quad <\Psi | J^{(3)} | \Psi > b^2 = m' (|C^{(m')}|^2 - |C^{(m'')}|^2).
\]

The complex conjugation operator has the form:

\[
\exp(-\text{i} \pi J^{(2)}) \exp(-\text{i} \pi J^{(2)}) D_{(m, m')}^{*},
\]

**The models of the electromagnetic field**

In accordance with the quantum formalism, to describe the electromagnetic field, besides \( E, H \) we introduce the wave function in the form:

\[
\Psi_{EH} = \text{EX}^{(1)} + \text{HX}^{(2)}, \quad \Psi_{A} = \text{AX}^{(3)} + A_0 C \quad X^{(0)} b, \quad F^{(1)} = E, \quad F^{(2)} = H, \quad F^{(3)} = A, \quad F^{(0)} = A_0 C \quad F^{(k)} = b^2 <\Psi | X^{(k)} >, \quad F^{(3)} = \text{EX}^{(1)} + \text{IF}^{(2)}.
\]

\( E, H \) and \( A \), \( A_0 \) may be considered as the amplitudes of the wave function of basic states of the electromagnetic field. The bases of the vector electromagnetic field directed along the axes of \( x_3 \) in the symmetric form \( X^{(k)}(k), X^{(0)} \) with respect to two observers \( X^{(3)}, X_3 \) have been found from the well-known transformation properties of the electromagnetic field and from the condition of invariance \( \Psi = \psi C \).
The bases \( X^{(n)} \), \( X^{(0)} \) correspond to a complete set of orthogonal basis functions for the state of the class \( 2|n| = 2 \). The wave function, the electric field and the magnetic field has the form.

Why is the sum of two electrical vectors equal to the electric vector?

Because basis functions \( X^{(n)} \), under their arbitrary addition at \( p \) constantly have property unchangeability, same functional dependence on angular dimensions (analog of property of form) in some rotated coordinate system, which always exists. Namely: for any vector states \( C = (C_1, C_2, C_3) \), \( \Psi = CX^{(p)} \), there is always such a rotated coordinate system \( X'_3 = C'|C' \) in which vector \( C' = (0, 0, |C|) \) and \( \Psi' = C'_3X^{(p)} \). That is, \( \Psi' \) have the same functional dependence with \( X^{(p)} \). Example:

\[
X^{(0)} = \exp(i\pi/2J_1)X^{(3)}_0, \quad X^{(1)} = \exp(-i\pi/2J_2)X^{(0)}_2, \quad X^{(2)} = \exp(i\pi/2) \Phi^{(0)}_1.
\]

According to the principle of superposition of states, the addition of vectors of the electric field and of the magnetic field coincides with the addition of their models \( \Psi \) as a function of the angles \( \phi \), \( \theta \) and \( \gamma \). For example:

\[
\Psi = EX^{(1)} \Psi = HX^{(2)}, \quad \Psi(E_1) + \Psi(E_2) = \Psi(E_1 + E_2).
\]

For the class 2, only vector basis, but not spin basis has this property of the same form. There are only three independent the forms for \( j = 1 \), except for their linear combination, which correspond to three functions \( X^{(0)}_0 \), \( X^{(1)}_0 \), \( X^{(2)}_0 \). The proof follows from the completeness of a 10-dimensional basis for class 2.

For \( \Psi \) of class 2 there are only 3 Lorentz invariant (Sventkovsky, 2004):

\[
C(\xi^{(1)})F = F(\xi)X^{(1)}, C(\xi^{(2)})E = 0, \quad C(0)X^{(0)} = 0 = F(0)X^{(3)} + F(0)X^{(0)} = \Psi_A.
\]

The real part of the invariants \( \Psi^{(k)} = F(\xi)X^{(k)} \) is obtained from the sum (difference) of the complex invariants, corresponds to the wave function of the electromagnetic field which has a zero projection of the (iso) vector operator \( \mathbf{j}_k \), \( \Psi^{(k)} \) at each point of Minkowski space.

\[
\Psi = \Psi_E X^{(1)} + \Psi_H X^{(2)}, \quad \Psi_{HE} = -\Psi_X^{(1)} + \Psi_X^{(2)}, \quad \Psi_{JH}^{(1)} = 0, \quad \Psi_{JX}^{(2)} = 0.
\]

The Lorentz transformations \( X^{(k)} \) with the condition of Sommerfeld about the invariance of the wave function \( \Psi = E X^{(1)} + H X^{(2)} \), provide the well-known Lorentz transformation properties of the fields \( E, H, A, A_0 \).

\[
\Psi = \Psi_{EH} X^{(1)} + \Psi_{HE} X^{(2)}, \quad \Psi_{HE} = -\Psi_H^{(1)} + \Psi_H^{(2)}, \quad \Psi_{JH}^{(1)} = 0, \quad \Psi_{JX}^{(2)} = 0.
\]

Mathematically the vectors can be added as objects having different directions, but in physics objects are always added as objects with one and the same direction. For example, a physical object is a set of projections of a vector. The addition of vectors will be regarded as the addition of a set of unidirectional projections. A vector has one to one correspondence with a set of its projections and vice versa. The projections are directed to the center of the vector for positive values of the projections and from the center for negative values. The basic states of the fields \( E, H, A \) which are directed along the axis \( x_3 \), have the form:

\[
X^{(1)}_3 = -\sin\theta \cos\phi, \quad X^{(2)}_3 = -\sin\theta \sin\phi, \quad X^{(3)}_3 = \cos\theta.
\]

To visualize the model of basic states in the center of the local observer, imaginary sphere of unit radius \( X^{(3)} \) is introduced; \( i_0, i_1, i_2, i_3 \) are spherical orts, given:

\[
X^{(1)}(\phi, \theta, 0) = i_0, \quad X^{(2)}(\phi, \theta, 0) = i_1, \quad X^{(3)}(\phi, \theta, 0) = i_2.
\]

The vector \( i_0 \) is assigned to the projection of cosine on the sphere. The vector \( i_1 \) is assigned to the projection of sine on the sphere. The vector \( i_3 \) is assigned to the projection of \( \cos(\theta) \), that are directed along \( i_1 \). Then replace the cosine of \( i_0 \) in \( X^{(1)}_3 \), sine on \( i_1 \) in \( X^{(2)}_3 \) and \( X^{(3)}_3 = \cos(\theta) \) will be considered as a set of projections of \( i_3 \), directed along \( i_1 \). The resulting visual model of the electromagnetic fields, correspond to a basis states \( X^{(1)}_3, X^{(2)}_3, X^{(3)}_3 \) and \( X^{(0)}_0 \), shown in Figure 2.

The polarity of the vector of electric field, the axial symmetry of the vector of magnetic field has been reflected in this mode. \( E, H, A, A_0 \) and \( X^{(1)}_3, X^{(2)}_3, X^{(3)}_3 \) under the spatial inversion are transformed identically \( i X^{(k)} = (-1)^k X^{(k)} \).

The generalized Lorentz group in the angular and matrix representation for transformations of spinors

The lie algebra of the groups Lorenz (Equation 5), Poincare (Equation 6) and its generators in the coordinate representation (Ohnuki, 1988); \( L = (M_{23}, M_{31}, M_{12}) \), \( K = (M_{02}, M_{02}, M_{03}) \), where \( M_{ij} = X_{ij} X_{ij} \), \( x_0 = 0 \), and \( P_{i} = -i \partial / \partial x_i \). \( P_0 = i \partial / \partial t \) are operators of momentum and energy, have the form:

\[
[L_1, L_2] = i\epsilon_{ijk} L_k, \quad [K_1, L_2] = i\epsilon_{ijk} K_k, \quad [K_1, K_2] = -i\epsilon_{ijk} L_k.
\]

\[
[P_1, P_2] = 0, \quad [K_1, P_2] = -i P_0, \quad [L_1, P_0] = i\epsilon_{ijk} P_k, \quad [K_1, P_0] = -i P_1.
\]

Operators \( Q^{(k)}(\phi, \theta, \gamma) \) have been introduced (Sventkovsky, 2004) in a symmetric form as a vector for the lower indices and an isovector for the upper indices, that is,

\[
Q^{(k)} = iX^{(p)} J + [X^{(p)} J], \quad Q^{(k)} = iX^{(p)} j + \bar{c}_{k}X^{(p)}, \quad j = iX^{(p)} k - \bar{c}_{mp} X^{(p)} k J^{(n)}.
\]

\( J \) is a linear, differential scalar Lorenz invariant operator that has properties: \( J \Psi = j \Psi \) for class 2]. It is possible
because the Wigner $D^j$ function can be decomposed into a homogeneous polynomial of degree $2j$ from $\psi_k$ (Equation 2), (Varshalovich, 1975), example $J=1/2 \ \psi_k \ \partial/\partial \psi_k$. Further, for the state of class $2j$, operator $\hat{J}$ will be replaced by $j$ everywhere. The operators $Q$ for $\Psi$ of class $2j$ have the form:

$$Q^{(3)}_i = i j \cos \phi \sin \theta + i \cos \phi \cos \theta \partial/\partial \phi - i \sin \phi \sin \theta \partial/\partial \phi + i \sin \phi \cos \theta \partial/\partial \phi$$

$$Q^{(3)}_2 = i j \sin \phi \cos \theta \sin \gamma \partial/\partial \phi + i \sin \phi \cos \theta \partial/\partial \phi$$

$$Q^{(3)}_3 = i j \sin \phi \cos \theta \sin \gamma \partial/\partial \phi + i \sin \phi \cos \theta \partial/\partial \phi$$

$$Q^{(3)}_4 = i j \cos \phi \sin \phi \cos \theta \partial/\partial \phi + i \sin \phi \cos \theta \partial/\partial \phi$$

The Lorentz transformation $v=|v|\chi^3$ with the (boost) generator $Q^{(3)}_3$, $p=3$ is independent of $\phi$ and $\gamma$ and is symmetrical with respect to two observers $X_3$ and $X^{(3)}$, hence $\phi'=\phi$, $\gamma'=\gamma$, $\theta(\chi)=v/c$ (13).

$$\exp(-i \cdot Q^{(3)}_3) \begin{bmatrix} X^{(3)}_3 \\ X^{(0)}_0 \end{bmatrix} = \begin{bmatrix} \chi(\gamma) & \sinh(\chi) \\ \sinh(\chi) & \cosh(\chi) \end{bmatrix} \begin{bmatrix} X^{(3)}_3 \\ X^{(0)}_0 \end{bmatrix}$$

The Lorentz transformations in Minkowski space and in the space of orientations respectively of four-dimensional vectors $A, A_0$ and $X^{(3)}, X^{(0)}_0$, bivectors $E, H$ and $X^{(1)}, X^{(2)}$, as well as spinors $\text{C}$ and $\Psi=\xi^{(4)}$ are opposite, inverse to each other, but the transformations of the vectors under the spatial rotation are the same. This ensures fulfillment of Sommerfeld condition about Lorentz invariance:

$$\Psi = AX^{(3)} + A_0 X^{(0)}_0 c$$

$$\Psi_{EH}=EX^{(1)}+HX^{(2)}_0, \quad \Psi=\psi \text{C}.$$
The Lorentz transformation for angular variables which was obtained earlier directly follows from the Lorentz transformations of spinors:

$$\xi^{(z)}_{m} = \exp(i \chi Q^{(z)}_{m}) \xi^{(z)}_{m}, \quad \text{or} \quad \xi^{(z)}_{m'} = \exp(\pm i \chi m) \xi^{(z)}_{m},$$

$$C_{m'} = \exp(\mp m \lambda C_{m}), \quad \exp(\chi) = \sqrt{(1 + V/c)/(1 - V/c)},$$

$$\tan(\theta/2) = \exp(-\chi)\tan(\theta/2).$$

These transformations of angles correspond to the known transformation of angles for polarized light with direction velocity along the axis $X^{(3)}$ and velocity $v' = -v$, (Pauli, 1958).

The Casimir operators of the Lorentz group in angular representations are operators $J^2, Q^{(3)}$, $J, Q^{(3)}$ have been obtained from the Casimir operators $K^2, L, K$ of the Lorentz group by replacing the generators of the Lorentz group $L, K$ by $J, Q^{(3)}$. The irreducible representations of the Lorentz group are characterized by a parameter of numbers corresponding to the eigenvalues of the operators $Z_{\pm}$, where $Z_{\pm} = (J \pm iQ^{(3)})/2, [Z_{\pm}, Z_{\pm}] = 2Z_{\pm} = 0$.

The spinors $\xi^{(z)}(j)$ are transformed, respectively on irreducible representation $(j, 0)$ and $(0, j)$ because $Z_{\pm} = \pm j(j+1)\xi^{(z)}(j), \quad Z_{\pm} = 0, \quad J_{\pm} = \pm j\xi^{(z)}(j), S_{\pm} = \pm \xi^{(z)}(j) S$.

The matrix representations of these two-irreducible spinor representation of the Lorentz group for an arbitrary $j$ can be obtained from (7), $p = 3$ by replacing the operators $J_{\pm}Q^{(3)}_{k}$ on their matrix representations in the spinor $j$, $\psi = \xi^{(j)}$ or $\psi = \xi^{(j+1)}$, as $\langle \psi | Q^{(3)}_{k} | \psi \rangle$.

The elements of $\xi^{(j)}_{m}$ whose Lorenz transformation has no an additional component are the eigenfunctions of $Q^{(3)}_{m}$.

$$Q^{(3)}_{m} \xi^{(j)}_{m} = \pm j \xi^{(j)}_{m}, \quad J_{3} \xi^{(j)}_{m} = m \xi^{(j)}_{m}$$

The bivectors $X^{(1)}, X^{(2)}$ are transformed respectively on irreducible representations $(1, 0)$ and $(0, 1)$ of the Lorentz group, because $Z^{(1)}X^{(1)} = X^{(1)}(1 \pm 1)$. The four-vector $X^{(3)}$ and $X^{(0)}$ are transformed on irreducible representation $(1/2, 1/2)$, because $Z^{(3)}X^{(3)} = 3/4X^{(3)}$. Thus, the representation of the Lorentz group (Equation 7) for the class 2 in 10-dimensional basis $\psi = X^{(0)}$ splits into irreducible vector representations for the basis $X^{(3)}$ and $X^{(0)}$, and into adjoint representation for the real basis $X^{(1)}$ and $X^{(2)}$.

**Definitions**

The Generalized Lorentz group (Equations 1, 7 and 8) is the group consists of 16 generators $J, J_{3}, J^{(0)}$, and $Q^{(0)}_{k}$ which was obtained by combining the known angular representation of the Lorentz group (Equation 7) (Sventkovsky, 2004) and its transposed angular representation.

$$[Q^{(0)}_{i}, Q^{(p)}_{k}] = i\delta_{k} \epsilon_{rpm} j^{(m)} - i \delta_{kp} \epsilon_{mkn} J_{n}, \quad [Q^{(p)}_{j}, J^{(n)}] = i\epsilon_{jkn} Q^{(n)}_{p}$$

The generalized group provides symmetry between the representation and transverse representation of the group or between the vector rotations of the original local observer and the isovector rotations of the rotated local observer, it is illustrated in Figure 3. The symmetry operator $W$ retains the invariance of the Lie algebra of the generalized Lorentz group $Q^{(n)}_{k} = (-1)^{(k+m)} W Q^{(k)}_{n}$.

Matrix representations of the generators of the generalized Lorentz group (Equations 1, 7 and 8) in the basis bi-spinor, $j = 1/2$ corresponding the replacement of $J_{3}, J^{(0)}, Q^{(0)}_{k}$, $J$ by $S_{0}^{(j)}, S_{j}, S_{j}^{(0)}, S_{j}^{(1)}$, $j$ matches 16 basis elements of the full Clifford algebra formed Dirac's gamma matrices (Fluge, 1974). The proof uses identities:

$$J_{n} \psi = \psi S_{0}^{(n)}, \quad J^{(0)} \psi = \psi S^{(0)}, \quad S_{j}^{(0)} \psi = -i \exp S_{0}^{(0)} S_{j}^{(0)}, \quad S_{j}^{(1)} \psi = \psi g_{0}, \quad 2J^{(0)} \psi = \psi \bar{g}_{0}, \quad 2Q^{(0)} \psi = \psi g, \quad 2Q^{(1)} \psi = \psi \bar{g}, \quad \langle \psi | J_{n} \psi \rangle = S_{0}^{(k)}$$

Where $g_{0}, \bar{g}_{0}$ and $g, \bar{g}$, $\gamma$-gamma Dirac matrices in the Weyl basis

$$g_{0} = (0, 1), \quad g = (0, -1), \quad \bar{g} = (1, 0), \quad g_{0} = (1, 0)$$

The infinitesimal generator of the Lorentz group $L_{k}$ and $K_{0}$ (Ohnuki, 1988) are identical to matrices $\langle \psi | J_{n} | \psi \rangle = \langle \psi | S_{j}^{(0)} | \psi \rangle = \langle \psi | S_{j}^{(1)} | \psi \rangle$ by using the basis $\psi = (X^{(0)}, X^{(3)}, X^{(1)}, X^{(2)}).$ This can be easily checked using (13). The study can also verify that ten generators of the Poincare group in angular (spinor) representation $J, Q^{(3)}, Q^{(0)}, iJ^{(1)}$, for $p = 3$, which were obtained using the generators of the generalized Lorentz group, have the same Lie algebra (Equations 5 and 6) of the ten generators of the Poincare group $L,K,P$ and $P_{0}$ where $Q^{(3)} = (L, K, P, P_{0})$. Four-dimensional vector $(P^{(1)}, P^{(0)}) = (Q^{(3)}, iJ^{(3)})$ can be regarded as analogous to the momentum operator in the Lie algebra of angular variables, since they have the same Lie algebra as Poincare group. It is illustrated in Figure 4.

The study can also verify using the Baker-Campbell-Hausdorff formula that generators of the Poincare group in angular representation have the known transformation properties under the Lorentz transformation, $(J, Q^{(3)})$ transformed as bivector, $(Q^{(0)}, iJ^{(1)})$ transforms as four-vector, vector momentum, $(Q^{(0)}, iJ^{(1)})$ transform as angular. Generalized Lorentz group is realized in the space of orientations.

The Pauli-Lubanski vector in the operator angular representation has the equivalent form $W_{\psi m}(P, J), \bar{W}_{\psi} = P_{0}J - (PQ^{(3)})$ that is obtained from Pauli-Lubanski vector by replacing the matrices $L$ and $M$ by the operators $J^{(3)}$. The operators $W_{\psi}$ and $\bar{W}$ in the matrix representation $J, Q^{(3)}$ in the corresponding basis is identical to the original Pauli-Lubanski vector.

The second Casimir operator of the Poincare group for the seven-dimensiional space has the equivalent form $(W_{\psi}, \bar{W})$ that is obtained from the second Casimir operator by replacing the Pauli-Lubanski vector by Pauli-Lubanski vector in angular representation.
The generalized Dirac, Maxwell, Weyl equations

The operator part of the Poincare invariant equations for the wave function which has the momentum operators in the first degree are invited to express in symmetric form an equal to the scalar product of two four-dimensional vectors of the momentum operators for space-time and for space of the orientations. We have:

\[ N^{(1)} = P^{(1)} P - P^{(1)}_0 P_0 \]
\[ N^{(2)} = Q^{(2)} P - J^{(1)} P_0 / c. \]

Thus Poincare invariant equations for the wave function can consist of two equations have different spatial parities corresponding to an even operator:

\[ N^{(1)} = \hat{P} N^{(1)} \]
\[ N^{(2)} = -\hat{P} N^{(2)}. \]

These equations will be referred to as the generalized Dirac, Maxwell, Weyl equations.

The generalized Maxwell equations for the class \(2j=2\), describing the spinless state and its analogue have the form (Equations 9 and 10):

\[ \Psi = EX^{(1)} + HX^{(2)}, \quad < \Psi | J | \Psi > = 0, \quad < \Psi | J^{(k)} | \Psi > = 0 \]
\[ N^{(1)} \Psi = 4\pi \Psi_C \]
\[ N^{(2)} \Psi = 0. \]  

where \( \Psi_C = IX^{(3)} + I_0 cX^{(0)} \), \( I = (I_1, I_2, I_3) \) is vector density of electric current, \( I_0 \) is the density of the electric charge.

Representation of generalized Maxwell Equations (9) and (10) in the basis \( X^{(8)} \) are equivalent to the Maxwell equations

\[ [PH] + P_0 E/c - i4\pi/c I, \quad (PE) = -i4\pi I_0, \]  
\[ [PE] - P_0 H/c = 0, \quad (PH) = 0. \]
For proof, we substitute in (9.10) the form Ψ, N(1) and N(2)
and use identity:

\[ J^{(1)} X_{p} = i c \langle x_{k} | k_p \rangle, \]
\[ J^{(2)} X_{k} = i j | x_{0} \rangle, \]
\[ J^{(3)} X_{k} = i c \langle x_{0} | k_p \rangle. \]

(13)

\[ J^{(3)} X_{0} = i c \langle x_{0} | k_p \rangle, \quad Q^{(3)} X_{k} = i j | x_{0} \rangle, \quad Q^{(3)} X_{0} = i c \langle x_{0} | k_p \rangle, \]
\[ Q^{(3)} X_{k} = i c \langle x_{0} | k_p \rangle, \quad Q^{(3)} X_{0} = i c \langle x_{0} | k_p \rangle, \quad Q^{(3)} X_{k} = i c \langle x_{0} | k_p \rangle, \quad Q^{(3)} X_{0} = i c \langle x_{0} | k_p \rangle. \]

(Eq. 14 and use identity)

The normalization of the wave function in the double
space of orientations (over the angles) at the point x1, x2, x3, is equal to the energy density of the electromagnetic
field: \( b^2 \psi_{EH}^2 / (8 \pi) = e^2 (E^2 + H^2) / (2 \pi) \).

The Poynting vector is written in the form:

\[ c b^2 \psi_{EH}^2 / (8 \pi) = \psi_{EH}^2 / (8 \pi). \]

The generalized Dirac equation j=1/2, 1, 3/2, ... have the
form (Equations 14 or 15). Representation (Equations 14
or 15) in the basis, j=1/2, (2) coincide respectively with
the ordinary Dirac equations (Equations 16) for the
electron \( \psi = C \) or with the Dirac equations (Equation 17)
for the unknown particles \( \psi = \psi \), \( m_0 \) is the mass.

\[ N^{(2)} \psi = m_0 c \sqrt{2} (2 h) \psi, \quad N^{(3)} \psi = m_0 c \sqrt{2} (2 h) \psi \]

(14)

(15)

For proof, we substitute in (Equations 14 and 15) the
form of \( N = N^{(1)} N^{(2)} \) \( N^{(3)} \psi = (\psi_1, \psi_2, \psi_3, \psi_4) \), and using the identities \( \psi_2 = g_p P g_0 P_0 / \sqrt{2} \psi_1 = \psi (g P g_0 P_0 / \sqrt{2}). \)

Equating to zero the coefficients at each from the
bases \( \psi_k \) in (Equations 14 and 15), identically we obtain
Dirac in chiral representation with matrices, respectively \( g \), \( g_0 \) (Ryder, 1987), (16) and \( g \), \( g_0 \). (Ryder, 1987):

\[ (g P g_0 P_0 / c + m_0 c / h) \psi = 0. \]

(16)

\[ (g P g_0 P_0 / c + m_0 c / h) \psi = 0. \]

(17)

The spinor Lorentz transformation of the \( N^{(3)} \)
when using a basis \( \psi = (\psi_1, \psi_2, \psi_3, \psi_4) \) corresponds to the
transformation group SL(2, C), relativistic spin group:

\[ \psi^T = \psi U, \quad U = \psi^T N^{(2)} \psi > U = U \psi^T (g P g_0 / c P_0) U, \quad \psi = (\xi^{(1/2) T}, \xi^{(1/2) T}), \]
\[ U = U^T \psi \text{ space rotation, } \xi^{(1/2) m} = \exp(\pm m c \chi) \xi^{(1/2) m} \text{ for Lorentz rotation.} \]

Solution of these Equations 14 and 15 for a particle
at rest, assuming that the term with the momentum operator
P vanish, correspond to standard representation of basis
and has the form:

\[ -J^{(1)} P c \psi = m_0 c / (2 h) \psi, \quad J^{(1)} \psi = \psi / 2 \]
\[ J^{(2)} P c \psi = \psi \psi, \quad J^{(2)} \psi = \pm \psi / 2 \]

(18)

(19)

Decisions have a zero balance between left and right

\[ \psi = C (\xi^{(1/2) T} + i \xi^{(1/2) T}), \quad \psi = C (\xi^{(1/2) T} - i \xi^{(1/2) T}), \]
\[ < | \psi |^2 = 0, < \psi \psi / \psi^2 > = 0. \]

At the inner inversion, electron becomes the positron
(Equations 16, 18 and 20) and on the contrary, but the
unknown particle remains unknown particle (Equation 17,
19 and 21):

\[ \hat{I} (\xi^{(1/2) T} + i \xi^{(1/2) T}) = \hat{I} (\xi^{(1/2) T} - i \xi^{(1/2) T}) \]
\[ \hat{I} (\xi^{(1/2) T} - i \xi^{(1/2) T}) = \hat{I} (\xi^{(1/2) T} + i \xi^{(1/2) T}) \]

(20)

(21)

Generalized Weyl equation with spin j=1/2 for Lorentz
invariant \( \psi = C \) (3) is identical to the Weyl equation
(Akhiezer and Berestetskii, 1965), for right or left neutrinos, have view:

\[ N^{(3)} \psi_{EH}^2 = 0, \text{ or, } (-P_0 c \pm P \sigma) C^{(3)} = 0. \]

(22)

Balance for the state \( \psi^{(3)} \) between left and right violated,
as \( J^{(3)} \psi_{EH}^2 = \psi_{EH}^2 / 2. \)

**Theorem 2**

Mirror symmetry of basis states with spin j=1/2. The
mirror basis \( \mu^{(1/2)} = (\xi^{(1/2) T} - i \xi^{(1/2) T}) \) is unique. No other bases
with this property exist. This basis is not changes under
the inversion \( I \mu^{(1/2)} = -i \mu^{(1/2)} \).

The proof follows from the completeness of the basis
and the choice of a basis in the form of linear
combinations of basis \( \xi^{(1/2) T} \) and \( \xi^{(1/2) T} \).

**Theorem 3**

Mirror antisymmetry of basis states with spin 1/2. There is
a subgroup of transformations \( \eta^{(1/2)} = \cos(\beta / 2) \xi^{(1/2)} + \sin(\beta / 2) \xi^{(1/2)}, \eta^{(1/2)} = \sin(\beta / 2) \xi^{(1/2)} + \cos(\beta / 2) \xi^{(1/2)} \) for any \( \beta \), when
the bases are transformed into each other under inversion \( I \eta^{(1/2)} = \pm \eta^{(1/2)} \).

The proof is similar. Thus, there is a plurality of bases
having mirror antisymmetry property \( \eta^{(1/2)} \), but there is
only one basis with mirror symmetry property \( \mu^{(1/2)} \). It is
additionally assumed that particles in rest with a nonzero
mass have a zero balance between the left and the
right-\( \eta^{(1/2)} \), \( \eta^{(3)} \psi^{(1/2)} = 0 \) which is implemented for \( \beta = \pi / 2 \).

The symmetry of Maxwell’s equations when \( (E,H) \) is
replaced by \((-\mathbf{H}, \mathbf{E})\) is called the electromagnetic duality. In general, there is a Heaviside-Larmor-Raynichia subgroup (HLR) (Konopelchenko, 1977):

\[ \mathbf{E} = \mathbf{E} \cos(\alpha) + \mathbf{H} \sin(\alpha), \quad \mathbf{H} = -\mathbf{E} \sin(\alpha) + \mathbf{H} \cos(\alpha). \]

These transformations correspond to the turn of the rotated local observer about axis \(X(3)\) by angle \(\alpha\) or to \(\Psi = \exp(\alpha \mathcal{J}^{(3)}) \Psi\), \(\gamma = \gamma \alpha\) in the framework transformations of generalized Lorentz group. Example, the use of the invariance of \(\Psi' = \Psi\) and \(\Psi = \mathbf{E} \mathcal{X}^{(1)} + \mathbf{H} \mathcal{X}^{(3)}, \\alpha = \pi/2, \mathcal{X}^{(1)}(y) = -\mathcal{X}^{(2)}(y+\pi/2), \mathcal{X}^{(2)}(y) = \mathcal{X}^{(1)}(y+\pi/2)\) are obtained conversion, yields transformations \(\mathbf{H} = -\mathbf{E}, \mathbf{E} = \mathbf{H}\). The transformations preserve balance between the left and right \(<\Psi|\mathcal{J}^{(3)}|\Psi> = 0, <\Psi|\mathcal{J}^{(3)}|\Psi'> = 0\).

The transformation \(\gamma = \gamma + \pi/2\) leads to transition into each other operators \(N^{(1)}, N^{(2)}\) that is \(N^{(1)}(\gamma) = N^{(2)}(\gamma+\pi/2), \quad N^{(2)}(\gamma) = N^{(1)}(\gamma+\pi/2)\).

In this case the mirror anti-symmetry of particles is replaced by the mirror symmetry and vice versa. The particle with mirror anti-symmetry under inner inversion and spatial inversion, converted into antiparticle, but particle with a mirror symmetry \(\gamma = 1/2\) converted itself, that is, not converted to the antiparticle (Equations 14 and 15), as \(\hat{\mathbf{P}} \mathcal{N}^{(2)} = -\mathcal{N}^{(2)}\) and \(\hat{\mathbf{P}} \mathcal{N}^{(1)} = \mathcal{N}^{(1)}\).

Transformation \(\gamma = \gamma + \pi/2\) of the generalized Dirac equation for the electron (Equations 14 and 16) leads to the generalized Dirac equation for the unknown particles (Equations 15 and 17) and vice versa.

Transformation \(\gamma = \gamma + \pi/2\) of the generalized Maxwell equations leads to the following changes: Maxwell's generalized equations (9 and 10) are replaced by Maxwell's generalized equations (24 and 25) that describe the existence of only magnetic charge: Equation 9 is replaced by Equation 24 and Equation 10 is replaced by Equation 25, with renaming electric charge (Equation 9) as magnetic charge (Equation 24) and renaming zero magnetic charge (Equation 10) as zero electric charge (Equation 25). Thus:

\[ \mathcal{X}_c = i \mathcal{X}^{(3)} + i_0 \mathcal{X}_0 \]

\[ \mathcal{X}^{(3)}(\gamma) = \mathcal{X}^{(3)}(\gamma+\pi/2). \]

\[ N^{(2)}(\gamma) = \mathcal{N}^{(2)}(\gamma+\pi/2), \quad N^{(1)}(\gamma) = \mathcal{N}^{(1)}(\gamma+\pi/2). \]

\[ \mathcal{N}^{(1)}(\gamma) = 0. \quad (24) \]

Matrix representations (Equations 23 and 24), when (Equation 13) is used, are identical to the Maxwell equations only in the case of existence of the magnetic charge.

Given the unified nature of the spin states for all \(j\), the uniform representation of the equations of Dirac and Maxwell in the form of the generalized equations of Dirac and Maxwell whose matrix representations coincide with Dirac’s and Maxwell’s equations, as well as because the magnetic monopole is an consequence of the existence of duality symmetries in electrodynamics, the following axiom is proposed:

The transformation \(\gamma = \gamma + \pi/2\) of the generalized Dirac equation and the generalized Maxwell equations leads to the same results. In other words, it is the transformation that implements the dual symmetry (generalized) of the Dirac equation and Maxwell's equations in the exchange of electric and magnetic charges. That is, a particle with electric charge (electron) is replaced by a particle with magnetic charge. Hence the unknown particles (Equations 15 and 19) are the Dirac monopole. The results are shown in Figure 5.

The transformation \(\gamma = \gamma + \pi\) corresponding to rotation about axis \(X(3)\) by angle \(\pi\) leads to a change in sign of the operators \(N^{(1)}, N^{(2)}\) which corresponds to a change in sign of the mass of particles (Equations 14 and 15), that is replacement of electron or monopole on antiparticle (Figure 5).

In nature, there are no elementary particles with spin \(j > 1/2\) which correspond to the generalized Dirac equation with non-zero mass and, as their should to be presented only in the basis \(\xi^{(3)}\) which has no extended component under the Lorentz transformations. Given the nature of the ladder operators in the generalized Dirac equation for \(\xi^{(3)}\), one can immediately see that such solutions do not exist.

**Superconductivity**

The known relationship \(\mathbf{H} = i [\mathbf{P}, \mathbf{A}]/c = i \mathbf{P} \mathbf{A}_0\) between the vector potential of magnetic field, potential of electric field and fields \(\mathbf{E}, \mathbf{H}\) is identical to equation \(N^{(1)} \Psi_A = \Psi_{EH}\), \(\Psi_A = \mathbf{A} \mathcal{X}^{(3)} + \mathbf{A}_0 \mathcal{X}^{(0)}\) and \(\Psi_{EH} = \mathbf{E} \mathcal{X}^{(1)} + \mathbf{H} \mathcal{X}^{(2)}\).

The generalized Dirac equation (Equation 25) of class 2 for Lorentz invariant \(\Psi = \Psi_{EH} / \Lambda \mathbf{A}_0\), where \(\Lambda\) is the constant length, using (Equation 13), splits into two equations for \(\Psi_{EH}, \Psi_A\):

\[ N^{(1)} \Psi = 1/\Lambda \Psi. \quad (25) \]

or \(N^{(1)} \Psi_{EH} = \Psi_A / \Lambda^2, \quad N^{(1)} \Psi_A = \Psi_{EH}\).

First equation is identical to the Maxwell equations (Equations 11 and 9) if it is denoted by \(j_0 = -\mathbf{A} / (4\pi^2), \quad j_0 = \mathbf{A}_0 / (4\pi^2)\) as the electric current. This corresponds to the first London equation for superconductivity where \(\Lambda\) is the depth of penetration, \(2\mathbf{h}/(\Lambda \mathbf{c})\) can be associated with the mass of a heavy virtual photon.

The generalized Maxwell equations whose representation are equivalent to the Maxwell equations (Equations 11 and 12) and describe a just right state or only left state with analog spin or chirality \(\pm 1\), have the following form:

\[ N^{(1)} \Psi^{(3)} = 4 \pi \Psi_c, \quad N^{(2)} \Psi^{(3)} = \mp 4 \pi \Psi_c, \quad \Psi^{(3)} = \mathbf{F} \mathcal{X}^{(2)}, \quad \Psi^{(3)} = \mathbf{E} \mathcal{X}^{(1)}, \quad j^{(3)} = \pm \Psi^{(3)}, \quad b^2 < \Psi^{(3)}, \quad |\Psi^{(3)}| > = 4 |\mathbf{E}\mathbf{H}|. \]
The proof is similar. The spins of the left and the right states are opposite to one another. The existence of high-temperature superconductivity is probably due to exchange of spin of the electromagnetic field in the chiral state and the orbital moment.

**Conclusion**

In the isotropic Minkowski space, the multicomponent wave function $C_k |k>$ corresponding to the spin, vector states equivalently is described by a one-component wave function $C_k \psi_k$ that depends on the position $x_1, x_2, x_3, t$ and the orientation $\varphi, \theta, \gamma$ of the local rotated observer. This corresponds to the replacement of the matrix basis $|k>$ by an operator basis $\psi_k$ that depends only on $\varphi, \theta, \gamma$ with the same transformation properties as for the matrix basis. $\varphi, \theta, \gamma$ may be interpreted as the possible orientation of the particle. Any angular dimensions (not are tied) does not depend on a specific spatial point since they are the same for all points of the space $x_1, x_2$ and $x_3$.

For a unified description of states with spin $j$, vector and tensor fields dependent on the orientation of the meter, a state of a class $2j$ was introduced as a class of functions $\Psi = \psi C$ which may be represented by a homogeneous polynomial of degree $2j$ of $D^{(1/2)}_{m, m'}$.

The known difficulties associated with the ambiguity of the transformations under the imbedding of a new space into the Minkowski space (Cartan, 1927) were successfully overcome by considering a well-known class of functions $2j$, (describing spinors, tensors) invariant under the Lorentz transformation and after determining the operators of the Poincare group for it in the angular representation.

The Lorentz group in matric representation was essentially expanded to the generalized Lorentz group due to the inclusion in it of transposed representations the Lorentz group, namely: Generators of two well-known groups in the angular representation corresponding to the rotation group SU(2), $J_n$ and the transposed rotation group SU(2), $J^{(k)}$ and also the generators of the Lorentz group $Q^{(p)}$ for different angular representations $p=1, 2$ and 3 form a generalized Lorentz group.

The symmetry of the generalized Lorentz group consists in its invariance with respect to the transpose operation in the matrix representation (or under the action of the operator $W$) and corresponds to the symmetry between the original observer and the rotated local observer.

The generalized Lorentz group besides transformations associated with the Lorentz group has an additional degree of freedom which can be considered as the transformations of internal symmetry. If the operators of the group $Q^{(p)}$, $J$ are in correspondence with the operators of the group $K, L$ in the Lorentz transformation, then the operators $J^{(k)}$ in the generalized group do not have such correspondence.

$J^{(k)}$ can be regarded as a generator group of the internal symmetry of particles, fields, $\Psi$ (Figure 4). The
spin projection and the directions of the vector field are invariant under transformation by means of $J^{(k)}$. Spinors and vectors are always transformed into spinors and vectors under transformations $J^{(k)}$. The generalized Lorentz group in the angular representation has been obtained by combining the internal symmetry group $J^{(k)}$ and the group of external symmetry with generators $Q^{(a)}$ and $J$ corresponding to the Lorentz group in the angular representation.

Inversion of space is always accompanied by a corresponding transformation of internal dimensions. Internal inversion: Transformation of $\Psi$ in the mirror state can be obtained via (continuous) rotation using the generator $J^{(k)}$ within the framework of transformations of the generalized group that preserve the invariance of the Lie algebra of the Lorentz group in angular representation. Therefore, the generalized Lorentz group, when spinors and vectors are transformed, includes the full Lorentz group. This fact partly explains that the parameter space for the SU(2) and SO(3) are different from each other twice.

Main laws nature equation of Dirac, Maxwell is like clockwork. All objects, wave function are moved, are transformed only with using generators of group, but do not move themselves. All objects can be moved over short distances with almost no distortion, but only objects that are eigenfunctions of generators (generalized) group. Figure 5 can be moved with the help of those generators without distortion on any distances. For example there is an identity: $\exp(i\alpha P_{\nu}) \exp(i\kappa x_{\nu}) = \exp(i(k(x_{\nu} + a)))$.

To obtain the first-degree equation on momentum, Dirac introduced a four-dimensional vector (from gamma matrices) independent of the coordinates.

Similarly the article introduces a four-dimensional vector $P^{(k)}$ from the new angular dimensions that do not depend from the coordinates of space-time.

The simplest equations of nature must be first-degree differential equations with respect to dimensions and to be Poincare invariant. For this purpose it is advisable to use the Casimir operator $P_{\nu}$ and $P_{\nu}$ of the Poincare group in which one of the two momentum operators is replaced by the momentum operator in the angular representation which is unique for $p=3$. As a result two real Lorentz invariants $N^{(1)}$, $N^{(2)}$, $P_{\nu} P^{(k)}=N^{(3)}-1 N^{(2)}$ have been obtained.

These operators correspond to the first Casimir operators for the seven-dimensional space and have been used to obtain Dirac, Maxwell, Weyl equations. The matrices, bases were equivalently replaced by operators, basis functions with the same transformation properties, when introducing angular dimensions. The generators of the Poincare group in the angular representation have been used to obtain the Dirac matrices and the resulting matrix at the momentum operator in the matrix form of Maxwell’s equations.

Generalized equation Dirac and Maxwell have two forms of representation $N^{(1)}$, $N^{(2)}$ which correspond to different parity at the spatial inversion. There are good reasons to believe that there are no other Poincare invariants except the first Casimir operator that are linear with respect to momentum operators.

The Lorentz invariants $N^{(1)}$, $N^{(2)}$ allow to write the equations of Dirac and Maxwell in a uniform form for the states of class $2j=1,2$ and to generalize these equations for any $j$.

The quantization of the electric, magnetic charge can be regarded as the quantization of the analogue of the spin $J^{(1)}$, $J^{(2)}$, (18), namely.

Generalized Dirac equation for spin 1/2 in the form $N^{(3)}(14)$ in the matrix representation is identical to the Dirac equation with matrices $g, g_{0}$ with corresponding to of Clifford algebra has a solution for a particle at rest, corresponding to a state with a mirror antisymmetry and has the projection $J^{(1)} \Psi = - \Psi / 2$ for electron, $J^{(1)} \Psi = \Psi / 2$ for positron. Scalar, Lorentz invariant has the form:

$$C_{0}g_{0}^{T} = < \Psi | J^{(1)} | \Psi > < \Psi | J^{(1)} | \Psi > .$$

Generalized Dirac equation for spin 1/2 in the form $N^{(1)}$, (Jante and Schroers, 2016) in the matrix representation is identical to the Dirac equation with matrices $g, g_{0}$ with corresponding to of Clifford algebra has a solution for a particle at rest, corresponding to a state with a mirror symmetry, and has the projections $J^{(2)} \Psi = \pm \Psi / 2$, which was named as unknown particle. Pseudo scalar Lorentz invariant, (Jante and Schroers, 2016) has the form:

$$C_{0}g_{0}^{T} = < \Psi | J^{(2)} | \Psi > < \Psi | J^{(2)} | \Psi > .$$

Generalized Weyl equation for spin 1/2 in the form $N^{(4)}$ (Jante and Schroers, 2016) is identical in the matrix representation to the Weyl equation for neutrino, antineutrino and has a solution $\Psi$, corresponding to a state with the projections $J^{(3)} \Psi = \pm \Psi / 2$. Since $\Psi = \psi_{3}$, (2) is also the eigenfunctions of the $Q^{(3)}$ and therefore $\Psi$ does not change shape when the Lorentz transformation. This situation corresponds to a particle moving with the speed of light along $x_{3}$ and which may be either right or left, $J^{(3)} \Psi = \pm \Psi / 2$ correspond antineutrinos $J^{(3)} \Psi = \pm \Psi / 2$.

Generalized Maxwell equations for class $2j=2$ in the form $N^{(1)}$, (Equation 9) and $N^{(2)}$, (Equation 10) in the matrix representations identical respectively the second pair of Maxwell’s equations for electrical charge (Equation 11) and the first pair of Maxwell’s equations for magnetic charge equal zero (Equation 12). It should be noted that generalized Maxwell’s equations (Equations 11 and 12) describe state $\Psi_{EH}$ without spin.

Principle of superposition of states always performed for states of class 2j in each point and for each orientation $\varphi, \theta$ and $\gamma$. The existence of the additional property of principle of superposition of states for the class $2j=1,2$ have been revealed in this paper. This property will be named to the property unchangeability (same) functional dependence wave function (analog of
form) of the angular dimensions when states are added. It was found that for spin states \( j=1/2 \) there are only two types of independent forms \( \psi_1, \psi_2 \) and for class \( 2j=2 \) there are three types of independent forms \( X^{(3)}_i \) that corresponds different to vector fields.

In accordance with the decisions of generalized Dirac equation, Weyl in nature can only be implemented in three types of point particles for spin 1/2, which are classified according to different types of symmetry and correspond with the three projections of analogue of the spin 1/2, \( J_3^{(3)} \psi = \pm \psi /2 \) respectively for electron at rest, for monopole at rest, for neutrino at flying. A particle and its antiparticle differ a sign of projection \( J_3^{(3)} \).

Taking into account that the solutions of the generalized equations, basis states correspond to eigenfunctions of generators of the generalized Lorentz group from \( \varphi, \theta \) and \( \gamma \), it can be concluded next: In nature for spin (vector) states is realized do not just Lorentz group, but generalized an Lorentz group. So some physical systems can be represented more accurately by using a generalized group Lorentz.

The determining role of the generators of the generalized Lorentz group in the formation of the Dirac, Maxwell, and Weyl equations (matrices for the momentum operators (Dirac matrix) and also of irreducible representations of the Lorentz group are shown.

A number of known transformations, such as inversion, Heaviside-Larmor-Raynich, charge conjugation, transition to different representations were equivalently unified and represented using the transformations of the group \( J^{(3)} \) within the framework of transformations of the generalized Lorentz group.

The superconductivity is proposed to be considered as a manifestation of the additional degree of freedom associated with the transformations of the generalized Lorentz group. The generalized Lorentz group in the matrix representation exists regardless of the use or non-use of angular variables. Three bases of the class \( 2j=2 \), \( \psi = X^{(1)}_{1,1}, X^{(1)}_r, \) \( (X^{(3)}_i, X^{(0)}_r) \) correspond to three irreducible representations of the Lorentz group \( (1, 0, 0, 1, 1/2, 1/2) \) and have three Lorentz invariant of \( \Psi \). The existence of three Lorentz invariants \( \Psi^{(3)} = F^{(3)} X^{(3)}_i, \psi_{EH}, \psi_A \) for the electromagnetic field \( E, H \), \( A, A_0 \) leaves the possibility of a transition from one state of \( \Psi \) to another in the framework of the transformations of the generalized Lorentz group and which are composed from linear combination of this three Lorentz invariants. One and the same electromagnetic field corresponding to the Maxwell equations, can correspond to different \( \Psi^{(3)} = F^{(3)} X^{(3)}_i \) or \( \Psi^{(1)} = \psi_{EH} \). The Lorentz invariants \( \psi_{EH}, \psi_A \) cannot describe state with spin, chirality, for example of photon, but \( \psi^{(3)} \) can, as \( b^0 \psi^{(3)} [J \psi^{(3)}] > \pm 4 [EH] \) is the direction and value of spin. Given the above, the following mechanism for the transition of a conductor to superconducting state proposed. The low-temperature superconductivity corresponds to a spontaneous transition to spinless state: \( \Psi = \psi_{EH} + \psi_A /\Lambda \).

The high-temperature superconductivity (in iron-based materials) can correspond to a spontaneous transition to left (right) state \( \psi^{(3)}_l \), that correspond to chiral superconductors \( J^{(3)} \psi^{(3)}_l = \pm \psi^{(3)}_r \).

The observed difference between left and right chiral superconductivity (Zyga, 2017), when a magnetic field is applied parallel to a superconducting chiral nanotube, electric signals travel in one direction only, can be explained by the existence of a spin of the electromagnetic field proportional to the Poynting vector but differently directed for the left and the right states.

Taking advantage of the fundamental provisions of the theory of groups, whereby the result of operations on one class \( 2j=2 \) automatically transferred to the result of the same operations on another class \( 2j=1 \) of the same group, has been offered the following axiom: The transformation \( \psi = \psi_{EH} + \psi_{EH} /2 \) leads to an exchange of forms \( N^{(1)} \) and \( N^{(2)} \) in generalized Dirac equation and in generalized Maxwell equations, formally leads to the same results, namely: Since generalized Maxwell’s equation for a particle of class \( 2j=2 \) with an electric charge is transformed into generalized Maxwell’s equation for particles with a magnetic charge. Matrix representation of this equation in the basis \( X^{(0)}_{k} X^{(0)}_r \) coincide with corresponding the equations Maxwell, consequently generalized Dirac equation of class \( 2j=1 \) for an electron is transformed into generalized Dirac equation for the Dirac monopole. Matrix representation of this equation in the basis \( j=1/2 \), bispinors, \( (2) \), also coincide with corresponding the Dirac equations. From the (generalized) equation it follows that is an unknown particle has a mirror symmetry for and coincide with Dirac monopole.

The difference between an electron and the Dirac monopole is difference in types of mirror symmetry, a monopole is a mirror particle and an electron has a mirror antisymmetry. The possibility of the existence of the Dirac monopole is determined by the possibility of the existence of a mirror particle.

The Dirac monopole in a state of rest with spin 1/2 has a unique basis with mirror symmetry, that is, it does not change under the inversion, but there are a lot of bases state of spin 1/2, with mirror antisymmetry (the particle passes into the antiparticle). This circumstance, which need to explore and the possible can dramatically reduce the likelihood of the occurrence of such particles (the Dirac monopole), when there is a transition to a unique basic state down to zero.

The subspace of angular dimension plays an important role in the formation of the basic laws of nature. The basic operator \( N^{(3)} \) is an analog of the Casimir operator and is written in a symmetric form with respect to the coordinate space and the double orientation space as products of the momentum operators for each spaces.

The existence only of three different (angular, spinor) purely complex representations of the Lorentz group simultaneously in the framework of the generalized
Lorentz group can be considered as a justification for the existence of three generations of leptons (electrons, muons, tau-leptons).

The existence only of three different (angular) purely complex representations of the transpose Lorentz group (as shown in Figure 3) simultaneously in the framework of the generalized Lorentz group can be considered as a justification for the existence of three color charge of quarks.

According to group theory, the result does not depend on the form of the representation. Because, in some cases, compared with the standard matrix approach, the use of operators from angular dimensions has a more obvious physical interpretation, simplicity and generality representation for any $j$.

CONFLICT OF INTERESTS

The authors have not declared any conflict of interests.

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