

*Full Length Research Paper***Some classifications on α -Kenmotsu manifolds****Saadet DOĞAN* and Müge KARADAĞ**

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In this paper, we investigate some curvature problems of α -Kenmotsu manifolds satisfying some certain conditions and we reach some classifications. We consider φ -recurrent α -Kenmotsu manifolds and we show that φ -recurrent α -Kenmotsu manifolds are also η -Einstein manifolds. Next, we study φ -Ricci symmetric α -Kenmotsu manifolds and we find this manifolds are Einstein manifolds too. In addition, we examine locally φ -symmetric α -Kenmotsu manifolds. Later we investigate this type manifold with quasi-conformally curvature tensor and concircular curvature tensor. In addition to these, we construct an example of α -Kenmotsu manifolds and we see that this example is a locally φ -symmetric α -Kenmotsu manifold.

Key words: α -Kenmotsu manifold, φ -recurrent, φ -Ricci symmetric, locally φ -symmetric, concircular curvature tensor, quasi-conformally curvature tensor, η -Einstein manifolds, Einstein manifolds.

INTRODUCTION

Janssens and Vanhecke (1981) define α -Kenmotsu manifolds. These are trans-sasakian of type $(0, \alpha)$ in J. A. Oubina's sense (Oubina, 1985). Öztürk et al. (2010) study about α -Kenmotsu manifolds satisfying some curvature conditions. Dileo (2011) write paper named "A classification of certain almost α -Kenmotsu manifolds". On the other hand De (2014) study globally φ -quasi-conformally symmetric α -Kenmotsu manifold and give some examples 3-dimensional α -Kenmotsu manifolds. We generally have interest on conditions about curvature tensor, because curvature tensors play important role in geometry and physics. For example; concircular

transformation transforms every geodesic circle of a Riemannian manifold M into a geodesic circle. An interesting invariant of a concircular transformation is the concircular curvature tensor (Yano, 1940). In this paper, we study φ -recurrent α -Kenmotsu manifolds. In addition to this, we investigate φ -ricci symmetric α -Kenmotsu manifolds and show that φ -ricci symmetric α -Kenmotsu manifolds are Einstein manifolds. In differential geometry and mathematical physics, an Einstein manifold is a Riemannian or pseudo-Riemannian manifold whose Ricci tensor is

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proportional to the metric. They are named after Albert Einstein because this condition is equivalent to saying that the metric is a solution of the vacuum Einstein field equations (Besse, 1987). Next, we deal with locally φ -symmetric α -Kenmotsu manifolds and we prove some theorems about the scalar curvature of the manifolds. In addition to these, we consider quasi-conformally flat condition on this type manifolds. We find interesting results when we investigate concircularly flat condition on locally φ -symmetric α -Kenmotsu manifolds.

MATERIALS AND METHODS

Let $(M; g)$ be an $(2n + 1)$ -dimensional Riemannian manifold. We denote by ∇ the covariant differentiation with respect to the Riemannian metric g . The Ricci tensor of M are defined by

$$S(X, Y) = \sum_{i=1}^{2n+1} R(e_i, X, Y, e_i) \tag{1}$$

where $\{e_1, e_2, \dots, e_{2n+1}\}$ is a locally orthonormal frame and X, Y are vector fields on M . The Ricci operator Q is a tensor field of type $(1, 1)$ on M defined by

$$g(QX, Y) = S(X, Y) \tag{2}$$

for all vector fields on TM .

Let M be an $(2n+1)$ -dimensional C^∞ manifold and $\chi(M)$ the Lie algebra of C^∞ vector fields on M . An almost contact structure on M is defined by $(1, 1)$ tensor field φ , a vector field ξ and a 1-form η on M . If (φ, ξ, η) satisfy the following condition then (φ, ξ, η) is said to be almost contact structure,

$$\eta(\xi) = 1, \quad \varphi^2 = -I + \eta \otimes \xi \tag{3}$$

$$\varphi\xi = 0, \quad \eta \circ \varphi = 0 \tag{4}$$

where I denotes the identity transformation of the tangent space T_pM at the point of p . Then M equipped with (φ, ξ, η) almost contact manifold. M with metric tensor g and with a triple (φ, ξ, η) such that

$$g(\varphi X, \varphi Y) = g(X, Y) - \eta(X)\eta(Y) \tag{5}$$

and

$$g(X, \xi) = \eta(X) \tag{6}$$

where $X, Y \in \chi(M)$, is an almost contact metric manifold.

Let $(M^{2n+1}, \varphi, \xi, \eta, g)$ be an almost contact metric manifold and $\Phi(X, Y) = g(X, \varphi Y)$ is the fundamental 2-form of M . M is called almost α -Kenmotsu manifold, if the 1-form η and the 2-form Φ satisfy the following conditions:

$$d\eta = 0, \quad d\Phi = 2\alpha\eta \wedge \Phi \tag{7}$$

α being a non-zero real constant (Janssens and Vanhecke, 1981).

We have known that an almost contact metric manifold $(M^{2n+1}, \varphi, \xi, \eta, g)$ is said to be normal if the Nijenhuis tensor

$$N_\varphi(X, Y) = [\varphi X, \varphi Y] - \varphi[\varphi X, Y] - \varphi[X, \varphi Y] + \varphi^2[X, Y] + 2d\eta(X, Y)\xi$$

vanishes for any $X, Y \in \chi(M)$. Remarking that a normal almost α -Kenmotsu manifold is said to be α -Kenmotsu manifold ($\alpha \neq 0$) (Janssens and Vanhecke, 1981). Moreover, if the manifold M satisfies the following relations

$$(\nabla_X \varphi)Y = \alpha\{-g(X, \varphi Y)\xi - \eta(Y)\varphi X\} \tag{8}$$

and

$$\nabla_X \xi = \alpha(X - \eta(X)\xi) \tag{9}$$

then $(M^{2n+1}, \varphi, \xi, \eta, g)$ is called α -Kenmotsu manifold (Pitiş, 2007).

A Riemannian manifold (M, g) is called a φ -recurrent Riemannian manifold, if the curvature tensor R satisfies the following condition:

$$\varphi^2((\nabla_W R)(X, Y)Z) = A(W)R(X, Y)Z \tag{10}$$

where A is 1-form (De et al., 2009; Yıldız et al., 2009).

A Riemannian manifold (M, g) is called φ -Ricci symmetric, if its Ricci tensor S satisfies the following condition:

$$\varphi^2[(\nabla_X Q)Y] = 0 \tag{11}$$

for all vector fields X and Y in TM (Shukla and Shukla, 2009). A Riemannian manifold M is said to be locally φ -symmetric, if

$$\varphi^2[(\nabla_W R)(X, Y)Z] = 0 \tag{12}$$

for all vector fields X, Y, Z, W orthogonal to ξ . This notion was introduced by Takahashi (Binh et al., 2002), for a Sasakian manifold.

A Riemannian manifold (M, g) is called quasi-conformally flat if its quasi-conformal curvature tensor \bar{C} ,

$$\bar{C}(X, Y)Z = aR(X, Y)Z + b\left\{ \begin{matrix} S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX \\ -g(X, Z)QY \end{matrix} \right\} - \frac{r}{2n+1} \left(\frac{a}{2n} + 2b \right) [g(Y, Z)X - g(X, Z)Y] \tag{13}$$

satisfies $\bar{C} = 0$, where r is the scalar curvature of (M, g) .
 A Riemannian manifold (M, g) is called concircularly flat if its concircular curvature tensor Z ,

$$Z(X, Y)W = R(X, Y)W - \frac{r}{2n(2n+1)}\{g(Y, W)X - g(X, W)Y\}$$

satisfies $Z=0$, where r is the scalar curvature of (M, g) .
 On an α – Kenmotsu manifold M , the following relations are held (Janssens and Vanhecke, 1981):

$$S(X, \xi) = -2n\alpha^2\eta(X) \tag{14}$$

$$R(\xi, X)Y = \alpha^2[-g(X, Y)\xi + \eta(Y)X] \tag{15}$$

$$R(X, Y)\xi = \alpha^2[\eta(X)Y - \eta(Y)X] \tag{16}$$

$$S(\phi X, \phi Y) = S(X, Y) + \alpha^2 2n\eta(X)\eta(Y) \tag{17}$$

$$(\nabla_x \eta)Y = \alpha[g(X, Y) - \eta(X)\eta(Y)] \tag{18}$$

ϕ -RECURRENT α – KENMOTSU MANIFOLDS

Here, we find that a ϕ – recurrent α – Kenmotsu manifold is an η – Einstein manifold.

Theorem

A ϕ – recurrent α – Kenmotsu manifold is an η – Einstein manifold (Dogan, 2014).

Proof

Let (M, ϕ, ξ, η, g) be a ϕ – recurrent α – Kenmotsu manifold. In this case; Riemannian curvature tensor of M satisfy the following equation for all X, Y, Z and W in TM :

$$\phi^2[(\nabla_w R)(X, Y)Z] = A(W)R(X, Y)Z$$

From Equation (3), we get

$$(\nabla_w R)(X, Y)Z + \eta[(\nabla_w R)(X, Y)Z]\xi = A(W)R(X, Y)Z \tag{19}$$

for all X, Y, Z, W in TM . If we take the inner product of Equation (19) with $U \in \chi(M)$, we find

$$A(W)g(R(X, Y)Z, U) = -g((\nabla_w R)(X, Y)Z, U) + \eta((\nabla_w R)(X, Y)Z)\eta(U) \tag{20}$$

for all X, Y, Z, W, U in TM . Then the sum for $1 \leq i \leq 2n+1$ of the relation (20) with $X = U = e_i$ fields

$$A(W)S(Y, Z) = -(\nabla_w S)(Y, Z) + \eta[(\nabla_w R)(\xi, Y)Z]. \tag{21}$$

If we write ξ instead of Z , we get

$$A(W)S(Y, \xi) = -(\nabla_w S)(Y, \xi) + \eta[(\nabla_w R)(\xi, Y)\xi]. \tag{22}$$

From Equations (9), (14) and (16), we get

$$-2n\alpha^2 A(W)\eta(Y) = (2n+1)\alpha^3 g(W, Y) + \alpha S(Y, W) - \alpha^3 \eta(W)\eta(Y). \tag{23}$$

If we write ϕY and ϕW instead Y and W , respectively, we find

$$0 = (2n+1)\alpha^3 g(\phi W, \phi Y) + \alpha S(\phi Y, \phi W), \tag{24}$$

From Equations (5) and (17), we have

$$S(Y, W) = -(2n+1)\alpha^2 g(Y, W) + \alpha^2 \eta(Y)\eta(W) \tag{25}$$

for all Y, W in TM . Then, M is an η – Einstein manifold.

ϕ – RICCI SYMMETRIC α – KENMOTSU MANIFOLDS

Here, we find that a ϕ – Ricci symmetric α – Kenmotsu manifold is an Einstein manifold.

Theorem

Let (M, ϕ, ξ, η, g) be a ϕ – Ricci symmetric α – Kenmotsu manifold. Then M is an Einstein manifold.

Proof

Suppose that (M, ϕ, ξ, η, g) is a ϕ – Ricci symmetric α – Kenmotsu manifold. In this case; Ricci operator of M satisfy the following condition:

$$\phi^2[(\nabla_x Q)Y] = 0$$

for all X, Y in TM . Then, we find

$$-(\nabla_x Q)Y + \eta[(\nabla_x Q)Y]\xi = 0. \tag{26}$$

From this last equation, we have

$$-\nabla_x QY + Q\nabla_x Y + \eta(\nabla_x QY)\xi - \eta(Q\nabla_x Y)\xi = 0 \quad (27)$$

for all vector fields X, Y in TM . If we take the inner product of Equation (27) with $\xi \in \chi(M)$, then we find

$$-g(\nabla_x QY, \xi) + g(Q\nabla_x Y, \xi) + \eta(\nabla_x QY) - \eta(Q\nabla_x Y) = 0 \quad (28)$$

and we continue the process, we get

$$\begin{aligned} S(\nabla_x Y, \xi) - \eta(Q\nabla_x Y) &= 0 \\ -2n\alpha^2 \eta(\nabla_x Y) &= \eta(Q\nabla_x Y) \\ g(-2n\alpha^2 \nabla_x Y, \xi) &= g(Q\nabla_x Y, \xi) \end{aligned} \quad (29)$$

for all X, Y in TM . From Equations (2) and (29)

$$Q = -2n\alpha^2$$

and

$$QX = -2n\alpha^2 X$$

for all X in TM . In this case, we have

$$\begin{aligned} S(X, Y) &= g(QX, Y) \\ &= g(-2n\alpha^2 X, Y) \\ &= -2n\alpha^2 g(X, Y) \end{aligned}$$

for all X, Y in TM . Then the proof is complete.

LOCALLY φ -SYMMETRIC α -KENMOTSU MANIFOLD

Here, we prove that locally φ -symmetric α -Kenmotsu manifolds have constant scalar curvature. In addition to if this type manifolds are quasi-conformal flat, then the manifold is Einstein manifold. On the other hand, we find that if locally φ -symmetric α -Kenmotsu manifolds are concircular flat, then these manifolds have constant curvature and their curvature is given $\frac{r}{2n(2n+1)}$ (r is scalar curvature of M).

Lemma 1

Let $(M, \varphi, \xi, \eta, g)$ be a locally φ -symmetric α -Kenmotsu manifold. Then scalar curvature of M is constant.

Proof

Suppose that $(M, \varphi, \xi, \eta, g)$ is a locally φ -symmetric α -Kenmotsu manifold. That is; Riemannian curvature tensor of M satisfy the following equation

$$\varphi^2[(\nabla_w R)(X, Y)Z] = 0$$

where X, Y, Z and W are orthogonal to ξ . If we continue the process, we obtain

$$-(\nabla_w R)(X, Y)Z + \eta[(\nabla_w R)(X, Y)Z]\xi = 0 \quad (30)$$

for all X, W, Z orthogonal to ξ . Then the sum for $1 \leq i \leq 2n+1$ of the relation (30), we get

$$(\nabla_w S)(X, Z) + \eta((\nabla_w R)(X, \xi)Z) = 0.$$

In this case;

$$(\nabla_w S)(X, Z) + \eta \begin{bmatrix} \nabla_w R(X, \xi)Z - R(\nabla_w X, \xi)Z \\ -R(X, \nabla_w \xi)Z - R(X, \xi)\nabla_w Z \end{bmatrix} = 0$$

for all X, W, Z orthogonal to ξ . So, using Equations (9) and (15), we obtain,

$$\begin{aligned} (\nabla_w S)(X, Z) + \alpha^2 g(X, Z)\eta(\nabla_w \xi) - \alpha^2 \eta(Z)\eta(\nabla_w X) \\ + \alpha^2 g(\nabla_w X, Z) - \alpha^2 \eta(Z)\eta(\nabla_w X) - \alpha\eta(R(X, W)Z) \\ + \alpha\eta(R(X, W)Z) - \alpha\eta(W)\eta(R(X, \xi)Z) - \alpha\eta(W)\eta(R(X, \xi)Z) \\ - \eta(R(X, \xi)\nabla_w Z) = 0. \end{aligned}$$

If we continue the process, we get

$$\begin{aligned} (\nabla_w S)(X, Z) = -\alpha^2 g(\nabla_w X, Z) + \alpha^2 g(\nabla_w Z, X) + \alpha^3 \eta(W)g(X, Z) \\ - \alpha^3 \eta(W)\eta(X)\eta(Z) - \alpha^2 \eta(X)\eta(\nabla_w Z). \end{aligned} \quad (31)$$

M is locally φ -symmetric, so

$$\eta(X) = \eta(Y) = \eta(W) = \eta(Z) = 0.$$

Then we find

$$(\nabla_w S)(X, Z) = -\alpha^2 g(\nabla_w X, Z) + \alpha^2 g(\nabla_w Z, X). \quad (32)$$

If we write $X = Z = e_i$ and we take the sum for $1 \leq i \leq 2n+1$ of the relation (32), we obtain

$$dr(W) = 0$$

for all vector fields W in TM . Then, the proof is complete.

Theorem

Let $(M, \varphi, \xi, \eta, g)$ be a locally φ -symmetric α -Kenmotsu manifold. If M is quasi-conformally flat, then M is Einstein manifold.

Proof

Suppose that $(M, \varphi, \xi, \eta, g)$ is a locally φ -symmetric α -Kenmotsu manifold. Then $\bar{C}(X, Y)Z$ quasi-conformal curvature tensor of M vanishes for any X, Y, Z in TM . That is,

$$aR(X, Y)Z + b[S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY] - \frac{r}{2n(2n+1)}\left(\frac{a}{2n} + 2b\right)[g(Y, Z)X - g(X, Z)Y] = 0 \tag{33}$$

for all X, Y, Z in TM . If we write ξ instead of X and Z and later we take the inner product of Equation (33) with $W \in \chi(M)$, then we get

$$S(Y, W) = \frac{1}{b}\left\{a\alpha^2 + 2nb\alpha^2 + \frac{r}{2n+1}\left(\frac{a}{2n} + 2b\right)\right\}g(Y, W) + \frac{1}{b}\left\{-a\alpha^2 - 4nb\alpha^2 - \frac{r}{2n+1}\left(\frac{a}{2n} + 2b\right)\right\}\eta(Y)\eta(W). \tag{34}$$

If we use Lemma 1 and we consider locally φ -symmetric then r is constant and $\eta(Y) = \eta(W) = 0$ since Y and W orthogonal to ξ . So we have

$$S(Y, W) = \lambda g(Y, W)$$

$(\lambda = \frac{1}{b}\left\{a\alpha^2 + 2nb\alpha^2 + \frac{r}{2n+1}\left(\frac{a}{2n} + 2b\right)\right\})$. In this case, M is Einstein Manifold.

Theorem

Let M be a locally φ -symmetric α -Kenmotsu manifold. If M is concircularly flat then M has got constant curvature and its curvature is $\frac{r}{2n(2n+1)}$.

Proof

Suppose that M is a locally φ -symmetric α -Kenmotsu

manifold. If M is concircularly flat then we obtain

$$R(X, Y)W = \frac{r}{2n(2n+1)}\{g(Y, W)X - g(X, W)Y\}. \tag{35}$$

If we consider Lemma 1 and the Equation (35), then we complete the proof.

Example

$M = \{(x, y, z) \in R^3, (x, y, z) \neq (0, 0, 0)\}$, where (x, y, z) are the standard coordinates in R^3 . The vector fields

$$e_1 = \alpha z \frac{\partial}{\partial x} \quad e_2 = \alpha z \frac{\partial}{\partial y} \quad e_3 = -\alpha z \frac{\partial}{\partial z}$$

are linearly independent at each point of M . Let g be Riemannian metric defined by

$$g = \frac{dx^2 + dy^2 + dz^2}{\alpha^2 z^2}.$$

Then we find

$$g(e_1, e_3) = g(e_1, e_2) = g(e_2, e_3) = 0 \\ g(e_1, e_1) = g(e_2, e_2) = g(e_3, e_3) = 1.$$

Let η be the 1-form defined by $\eta(X) = g(X, e_3)$ for any $X \in \chi(M)$. Let φ be a (1,1) tensor field defined by $\varphi(e_1) = -e_2, \varphi(e_2) = e_1, \varphi(e_3) = 0$. If we define $\xi = e_3, \eta(X) = g(X, e_3)$ for all vector fields X in TM and use the linearity of φ and g , then we find

$$\eta(\xi) = 1, \varphi^2 X = -X + \eta(X)\xi, g(\varphi X, \varphi Y) = g(X, Y) - \eta(X)\eta(Y)$$

for all vector fields X, Y in TM . In this case, $(M, \varphi, \xi, \eta, g)$ is an almost contact metric manifold. Suppose that ∇ is Levi-Civita connection with respect to the metric g . For all $f \in C(R^3, R)$, we get

$$[e_1, e_2]f = e_1(e_2(f)) - e_2(e_1(f)) \\ = e_1(\alpha z f_y) - e_2(\alpha z f_x) \\ = 0$$

$$\begin{aligned}
 [e_1, e_3]f &= e_1(e_3(f)) - e_3(e_1(f)) \\
 &= e_1(-\alpha z f_z) - e_3(\alpha z f_x) \\
 &= \alpha z(-\alpha z f_{zx}) + \alpha z(\alpha z f_{xz} + \alpha f_x) \\
 &= \alpha e_1(f)
 \end{aligned}$$

and

$[e_2, e_3]f = \alpha e_2(f)$. In this case, from Kozsul's Formula, we find

$$\begin{aligned}
 \nabla_{e_1} e_1 &= -\alpha e_3 & \nabla_{e_2} e_1 &= 0 & \nabla_{e_3} e_1 &= 0 \\
 \nabla_{e_1} e_2 &= 0 & \nabla_{e_2} e_2 &= -\alpha e_3 & \nabla_{e_3} e_2 &= 0 \\
 \nabla_{e_1} e_3 &= \alpha e_1 & \nabla_{e_2} e_3 &= \alpha e_2 & \nabla_{e_3} e_3 &= 0.
 \end{aligned}$$

Let $X = ae_1 + be_2 + c\xi$ and $Y = \bar{a}e_1 + \bar{b}e_2 + \bar{c}\xi$ be vector fields in TM (Where $a, b, c, \bar{a}, \bar{b}, \bar{c} \in R$). Then we get $\phi Y = \bar{b}e_1 - \bar{a}e_2$. In this case;

$$\begin{aligned}
 (\nabla_X \phi)Y &= \nabla_X \phi Y - \phi \nabla_X Y \\
 &= \nabla_{ae_1 + be_2 + c\xi} (\bar{b}e_1 - \bar{a}e_2) - \phi (\nabla_{ae_1 + be_2 + c\xi} (\bar{a}e_1 + \bar{b}e_2 + \bar{c}\xi)) \\
 &= \alpha \{ -(\bar{a}\bar{b} - \bar{b}\bar{a})\xi - \bar{c}(-ae_2 + be_1) \} \\
 &= \alpha \{ -g(X, \phi Y)\xi - \eta(Y)\phi X \}
 \end{aligned}$$

for all vector fields X, Y in TM . Hence (M, ϕ, ξ, η, g) is an α -Kenmotsu manifold. With the help of above results we can find the following:

$$\begin{aligned}
 g(R(e_1, X)Y, e_1) &= -\alpha^2(\bar{b}\bar{b} + \bar{c}\bar{c}) \\
 g(R(e_2, X)Y, e_2) &= -\alpha^2(\bar{a}\bar{a} + \bar{c}\bar{c}) \\
 g(R(e_3, X)Y, e_3) &= -\alpha^2(\bar{a}\bar{a} + \bar{b}\bar{b})
 \end{aligned}$$

and

$$S(X, Y) = \sum_{i=1}^{2n+1} R(e_i, X, Y, e_i)$$

$$S(X, Y) = -\alpha^2 g(X, Y) - \alpha^2 \eta(X)\eta(Y).$$

Hence, M is an η -Einstein manifold. Now, we take X, Y, Z and W orthogonal to ξ . Then we can write

$$\begin{aligned}
 X &= ae_1 + be_2 \\
 Y &= \bar{a}e_1 + \bar{b}e_2 \\
 Z &= \tilde{a}e_1 + \tilde{b}e_2 \\
 W &= \hat{a}e_1 + \hat{b}e_2.
 \end{aligned}$$

In this case, if we compute $(\nabla_W R)(X, Y)Z$, we find

$$\begin{aligned}
 (\nabla_W R)(X, Y)Z &= \nabla_W R(X, Y)Z - R(\nabla_W X, Y)Z - R(X, \nabla_W Y)Z - R(X, Y)\nabla_W Z \\
 &= 0.
 \end{aligned}$$

Then,

$$\phi^2(\nabla_W R)(X, Y)Z = 0$$

for all vector fields X, Y, Z and W orthogonal to ξ . In this case, this manifold is a locally ϕ -symmetric α -Kenmotsu manifold. In Lemma 1, we show that scalar curvature of a locally ϕ -symmetric α -Kenmotsu manifold is constant. Actually, if we compute scalar curvature for all vector fields X, Y orthogonal to ξ , we see that

$$\begin{aligned}
 S(X, Y) &= -\alpha^2 g(X, Y) \\
 r &= \sum_{i=1}^3 S(e_i, e_i) = -3\alpha^2.
 \end{aligned}$$

Conflict of Interest

The authors have not declared any conflict of interest.

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